



PRECISE

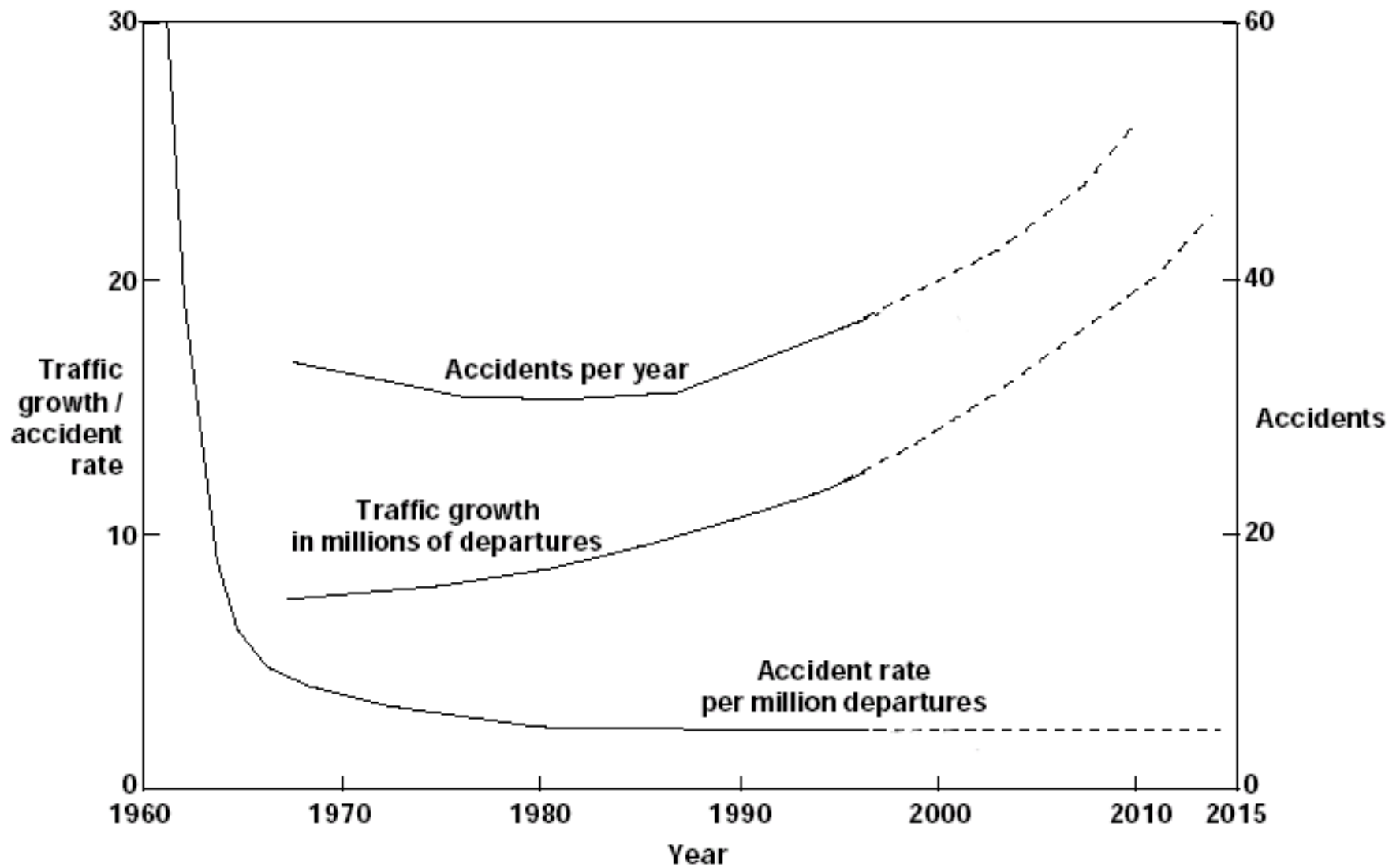
**Pathway Rendered Experimental Concepts
for InSITE SVS Experiment**

**Lance Prinzel, Ph.D.
NASA Langley Research Center**

Aviation Accident Trend



Aviation Safety Program: Synthetic Vision Systems





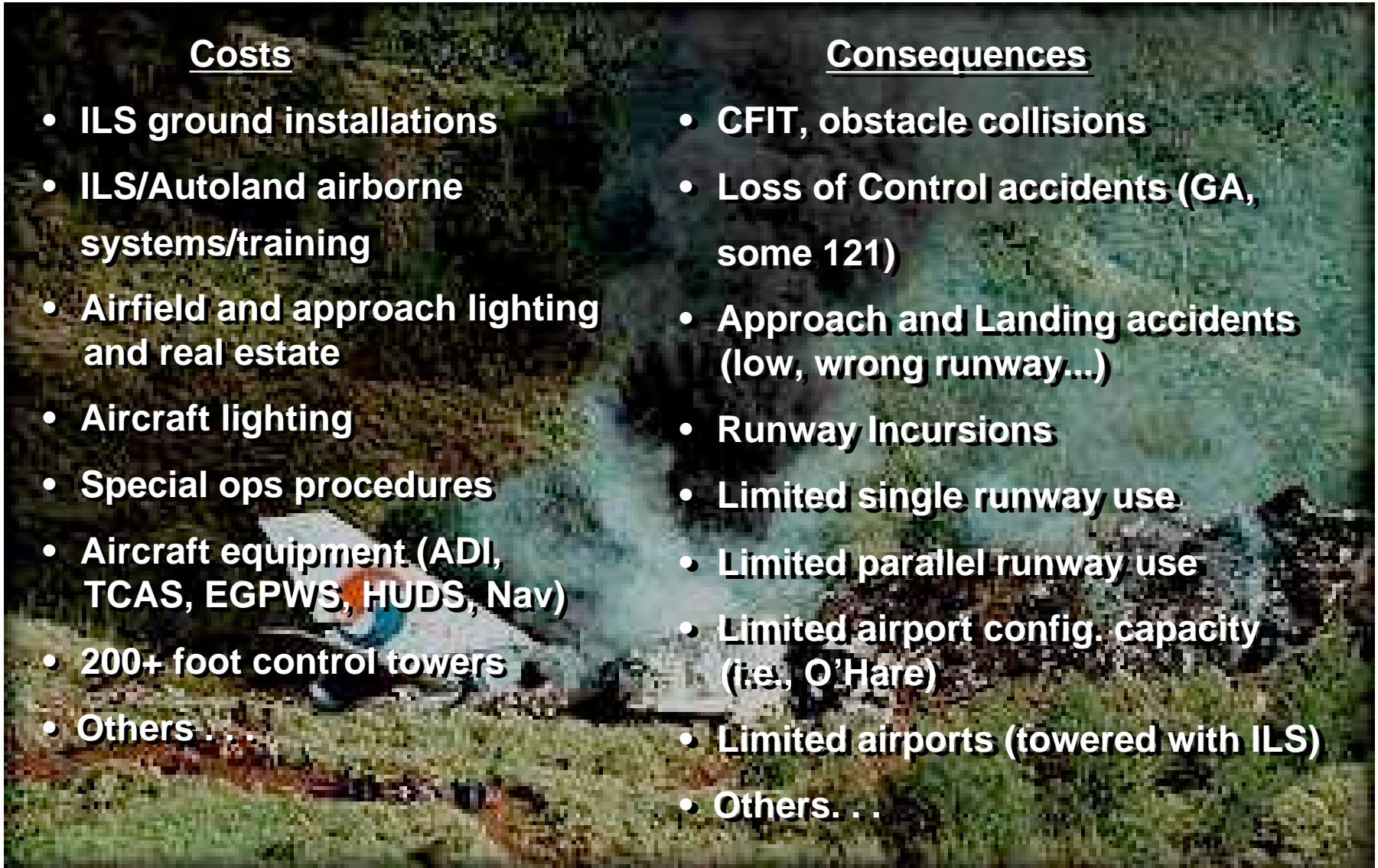
What the Need for Visibility Makes us Do

Costs

- ILS ground installations
- ILS/Autoland airborne systems/training
- Airfield and approach lighting and real estate
- Aircraft lighting
- Special ops procedures
- Aircraft equipment (ADI, TCAS, EGPWS, HUDS, Nav)
- 200+ foot control towers
- Others . . .

Consequences

- CFIT, obstacle collisions
- Loss of Control accidents (GA, some 121)
- Approach and Landing accidents (low, wrong runway...)
- Runway Incursions
- Limited single runway use
- Limited parallel runway use
- Limited airport config. capacity (i.e., O'Hare)
- Limited airports (towered with ILS)
- Others. . .





The Complete Solution: Synthetic Vision

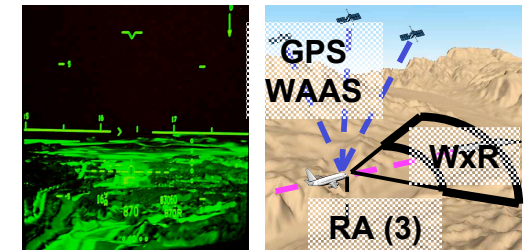
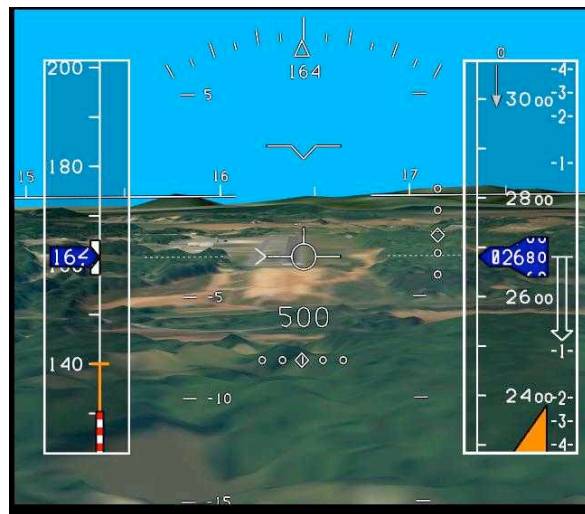
Aviation Safety Program: Synthetic Vision Systems



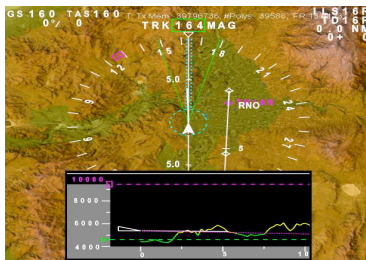
A database derived system utilizing precise GPS navigation & integrity-monitoring sensors (as required) to provide a unrestricted synthetic view of the aircraft's current external environment, regardless of weather or time of day



Worldwide Terrain & Obstacle Database



Advanced Sensors for Database Integrity & Object Detection



Real-Time Integrated Hazards Displays



Traffic Information & Surface Guidance

Future Commercial Cockpit



Aviation Safety Program: Synthetic Vision Systems





Benefits of Synthetic Vision for Aviation

Aviation Safety Program: Synthetic Vision Systems



- Cost-benefit analyses predict \$780 million dollar savings per year with synthetic vision technology with investment of 110K per aircraft
- Research has demonstrated operational benefits of synthetic vision and enhanced situation awareness for approaches to operationally complex and terrain challenged airports (Prinzel et al., 1999, 2000, 2001, 2002, 2003, Kramer et al., 2003).
- In addition to operational and economic benefits, there are significant aviation safety benefits. NASA research has demonstrated the efficacy of synthetic vision to mitigate spatial disorientation, CFIT, and runway incursions.
- A substantial amount of human factors research has also been conducted to help ensure a “human-centered” synthetic vision system



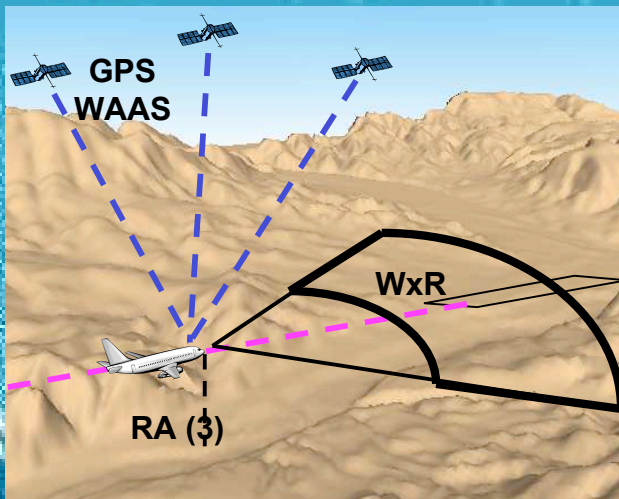
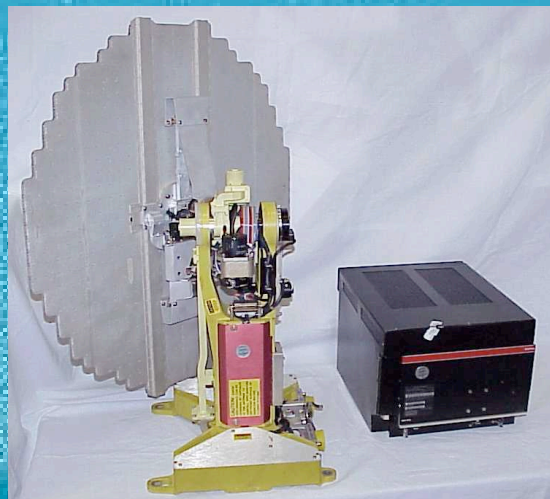
NASA Synthetic Vision Flight Test at Eagle Vail, Colorado Airport



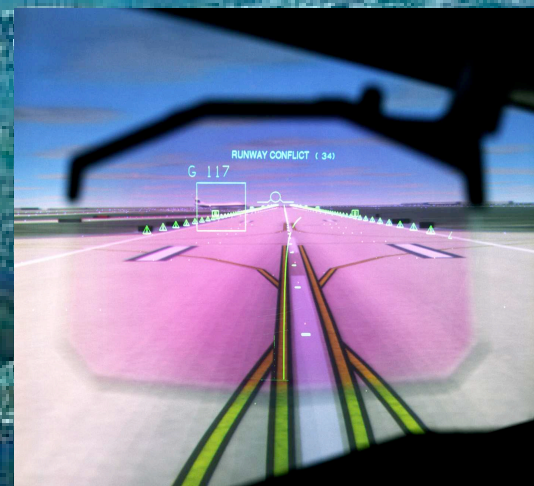
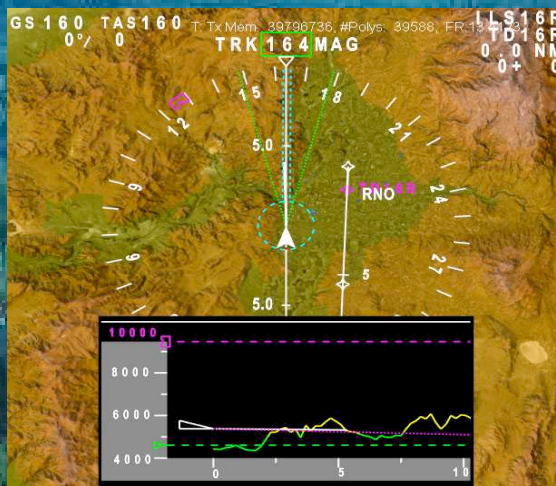
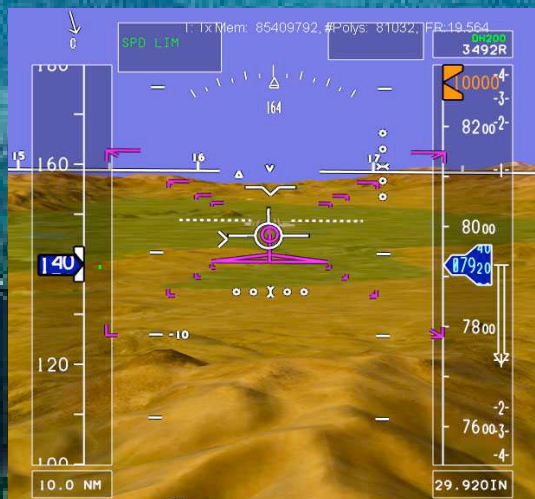
NASA Synthetic Vision Night Flight Test at Dallas-Fort Worth Airport



NASA Synthetic Vision GA Flight Test at Roanoke, VA Airport



INItial SVS Integrated Technology Evaluation





Experimental Objectives

Aviation Safety Program: Synthetic Vision Systems



- Evaluate four pathway / tunnel concepts
- Evaluate three guidance symbology presentations
- Evaluate concepts for visual approach under IMC
- Compare pathway and guidance concepts to baseline concept



Synthetic Vision Hybrid Texture Concept

Aviation Safety Program: Synthetic Vision Systems

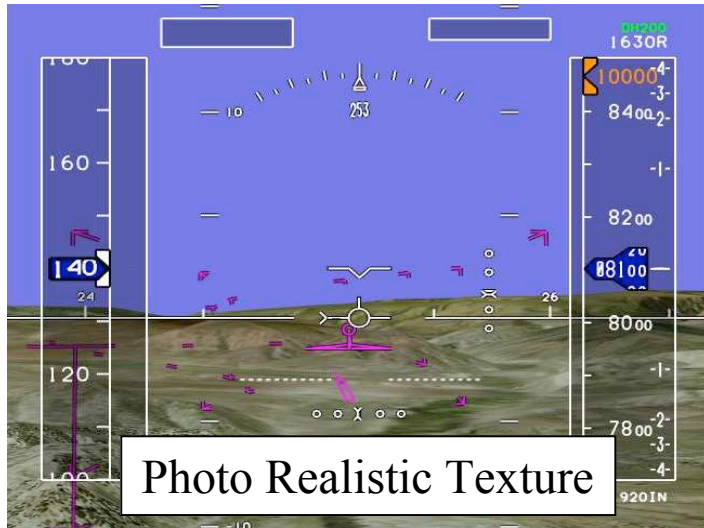
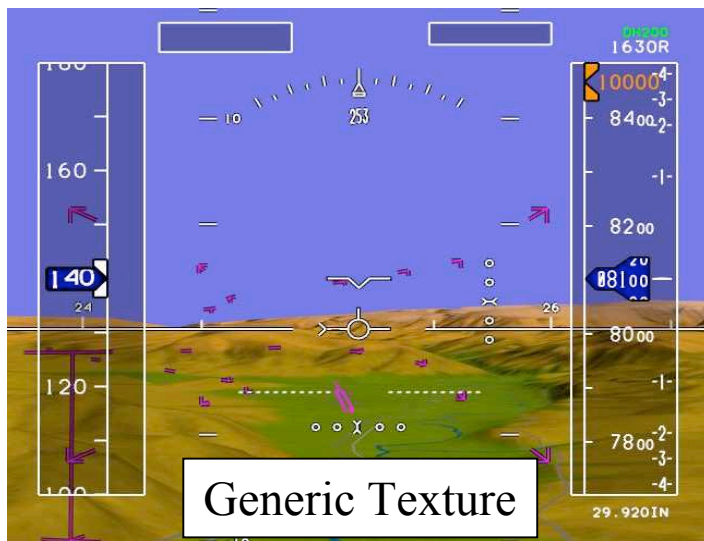
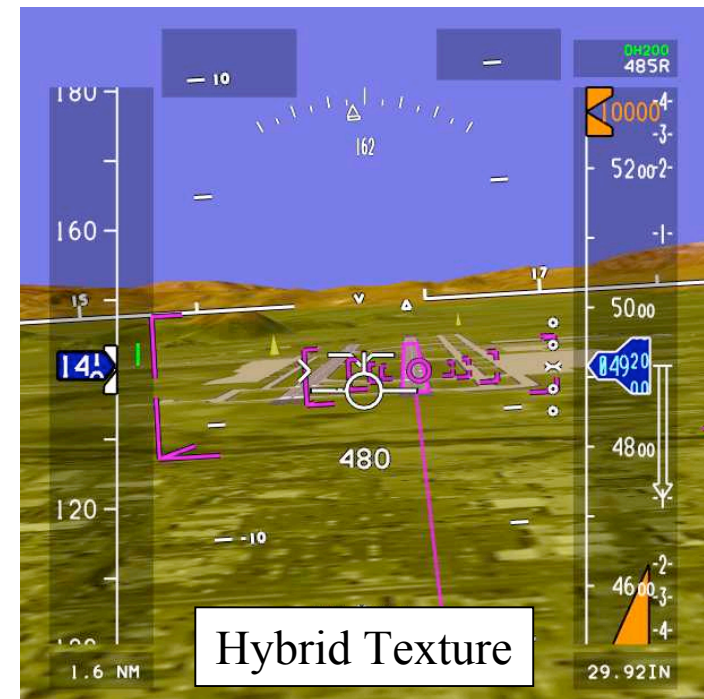
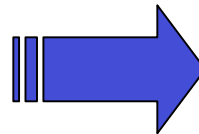


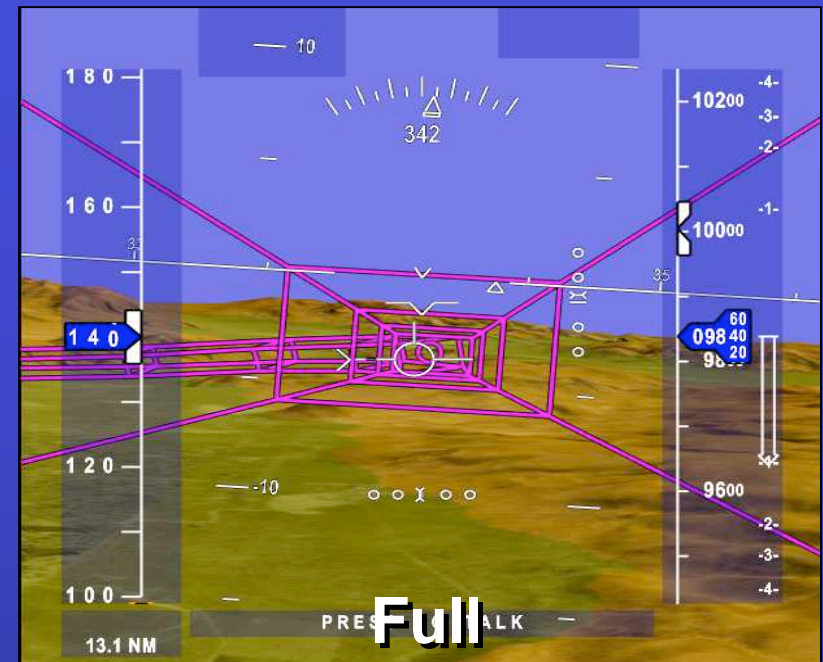
Photo Realistic Texture



Generic Texture



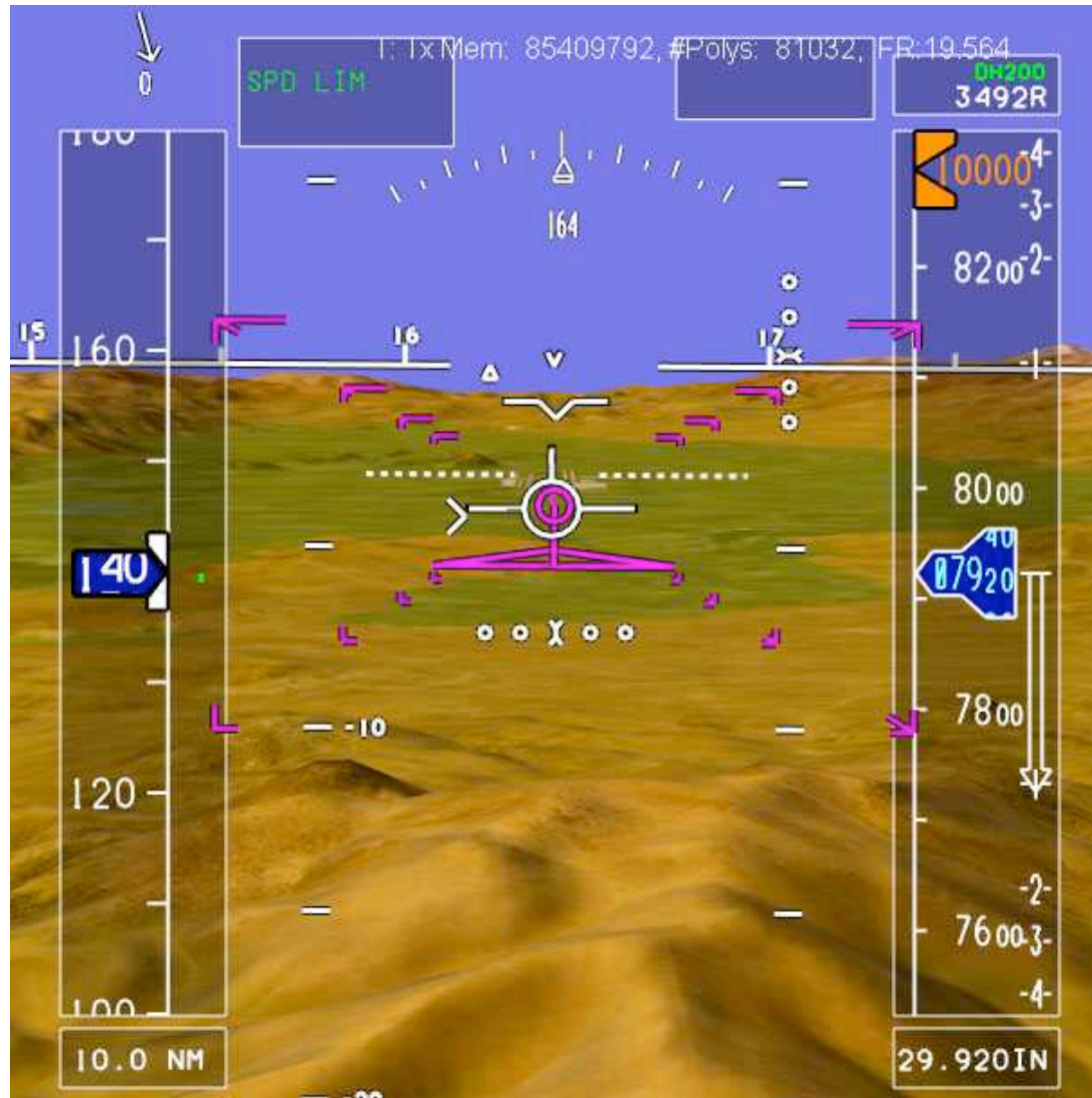
Hybrid Texture





Dynamic Tunnel Concept

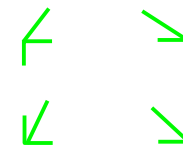
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Dynamic tunnel concept:

- Minimize Display Clutter When on Path
- Provide Enough Information to Reacquire Path When off Path

Tunnel Corners every .2 NM



1 dot wide (+/- $\frac{1}{2}$)
2 dots high (+/- 1)

Max 600' Wide
Max 350' Tall
Min 50' Tall

Notes: Fading and Number of Visible
Tunnel Segments Experimentally Varied



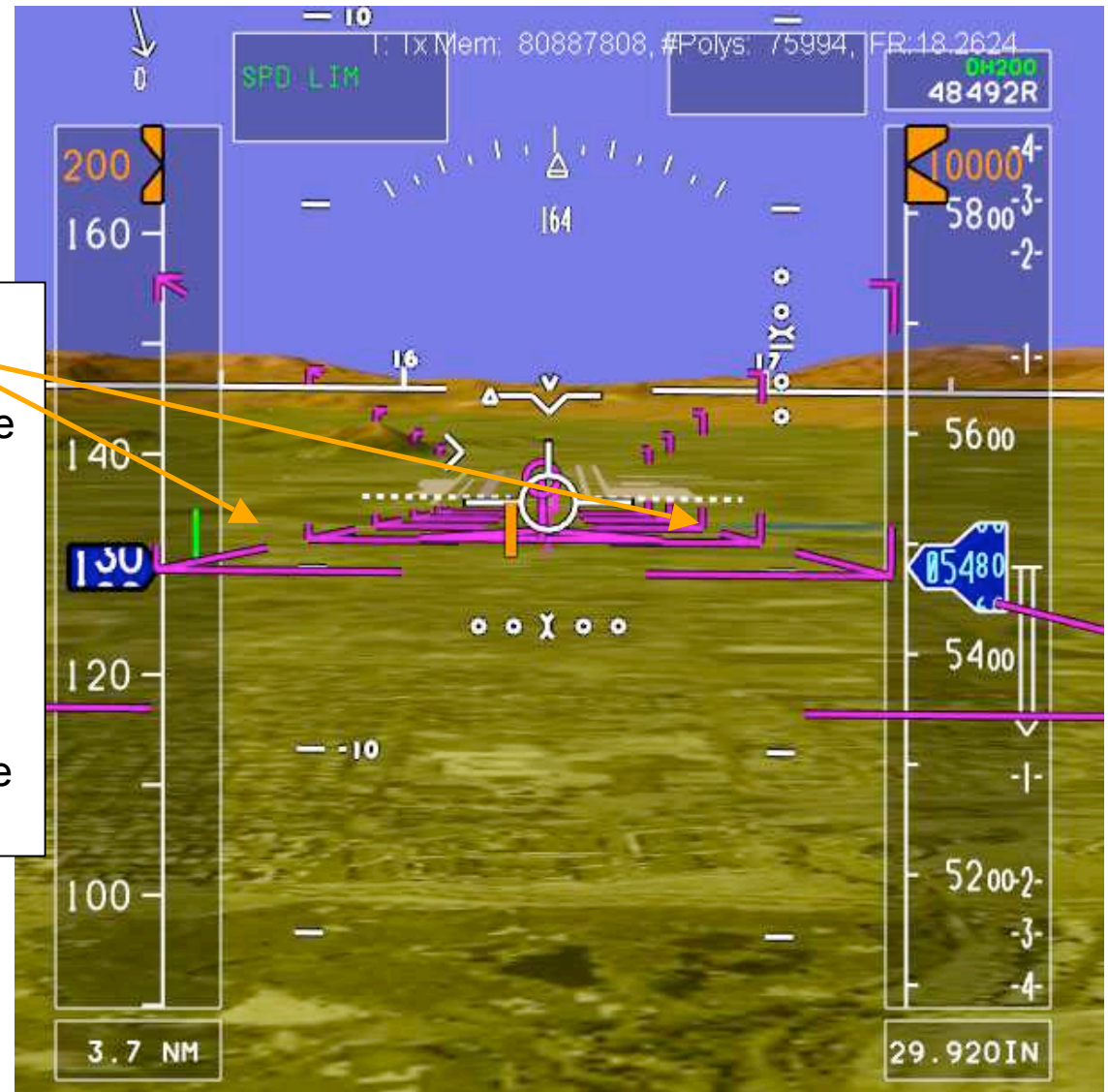
Dynamic Tunnel Concept

Aviation Safety Program: Synthetic Vision Systems



Path Deviation

- Tunnel corner lines lengthen in direction of deviation to indicate you're approaching tunnel edge.
- In this example, flight path marker is moving toward bottom of tunnel so those corner lines are lengthening. Once the flight path marker is at the tunnel bottom, there will be a solid line between the two tunnel corners.





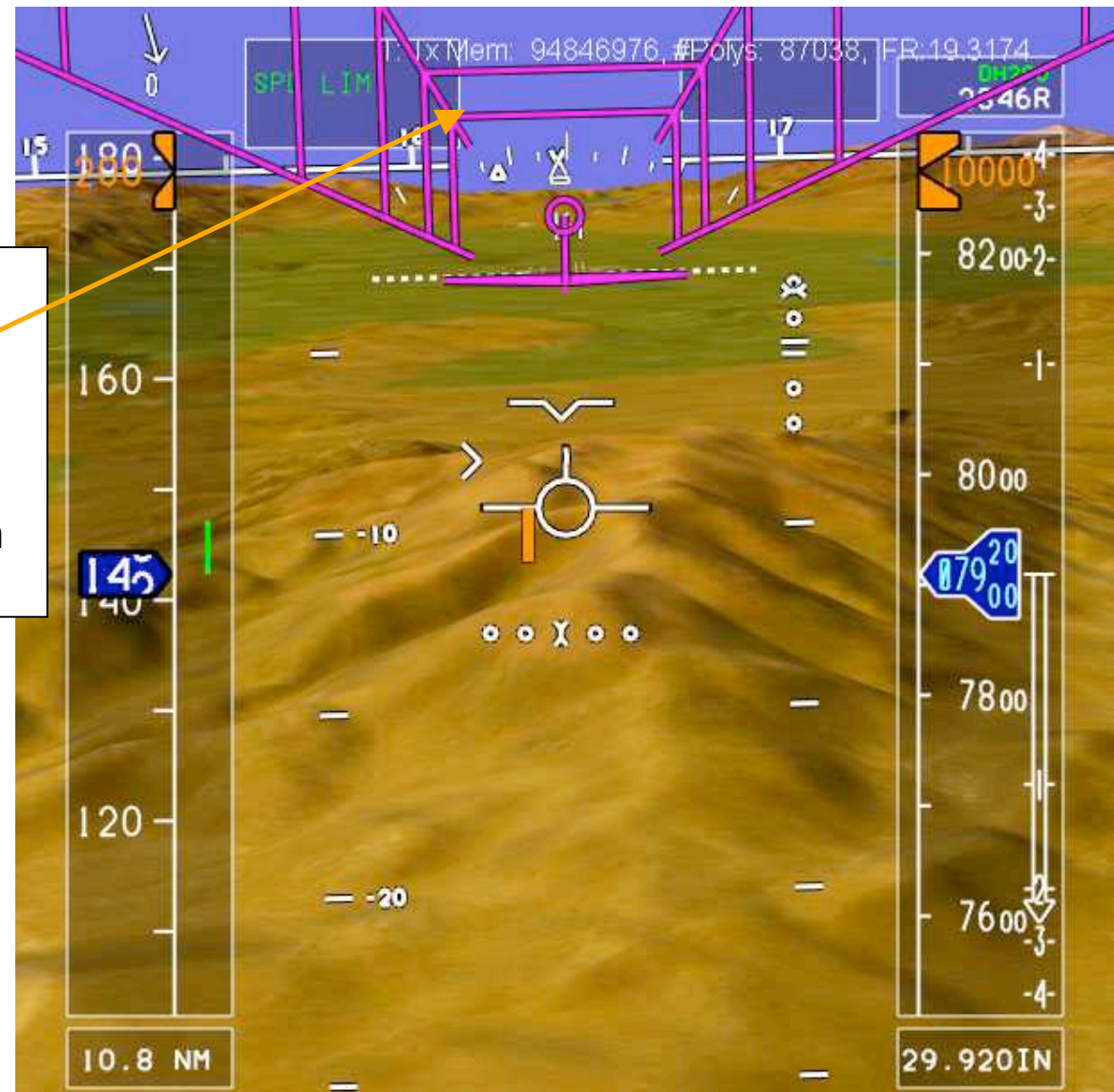
Dynamic Tunnel Concept

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Outside tunnel

- Fly into “trough” to reacquire path.
- In this example, flight path marker is below tunnel so the pilot should fly up into the tunnel opening to get back on path.





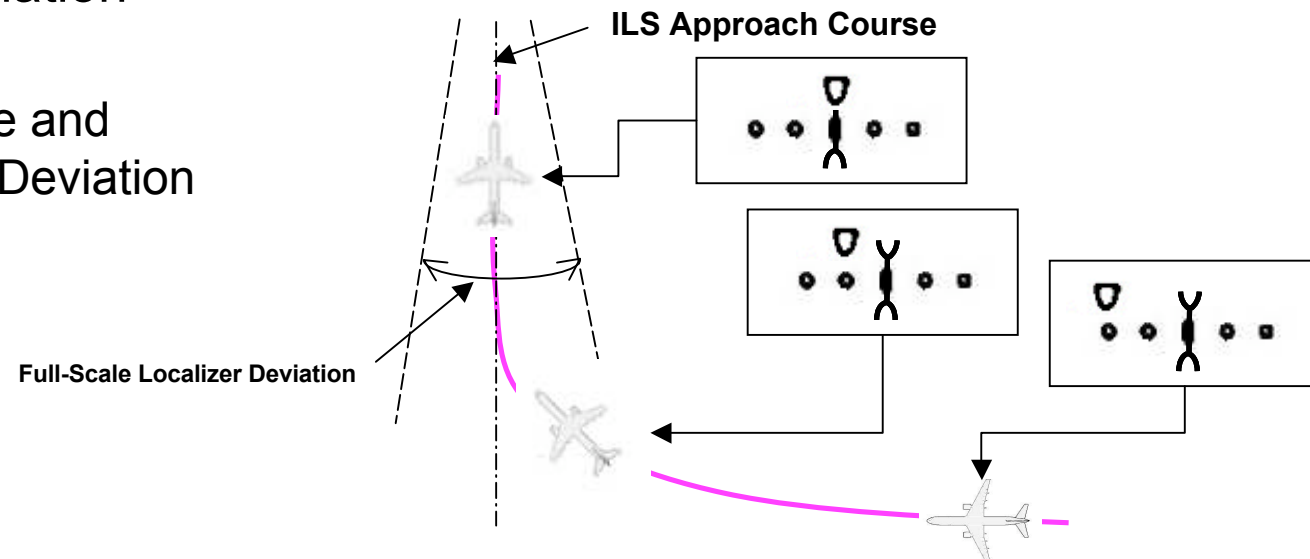
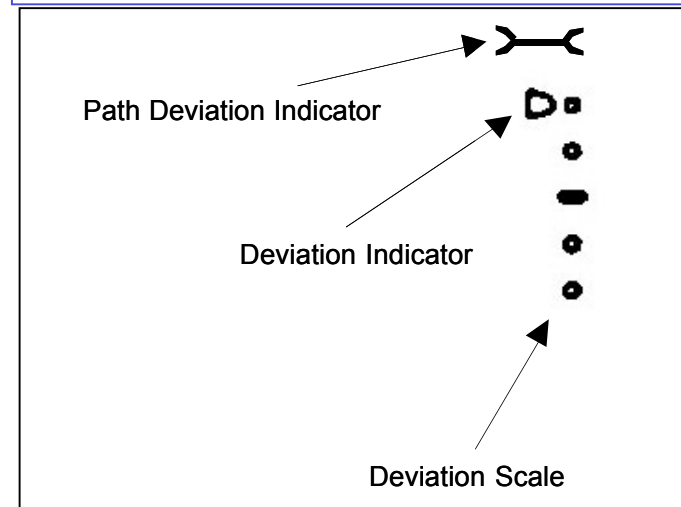
Path Deviation Indicators

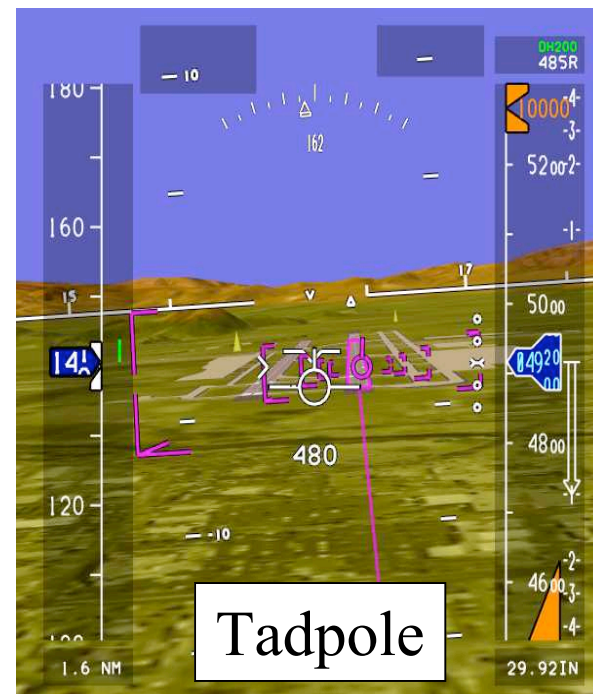
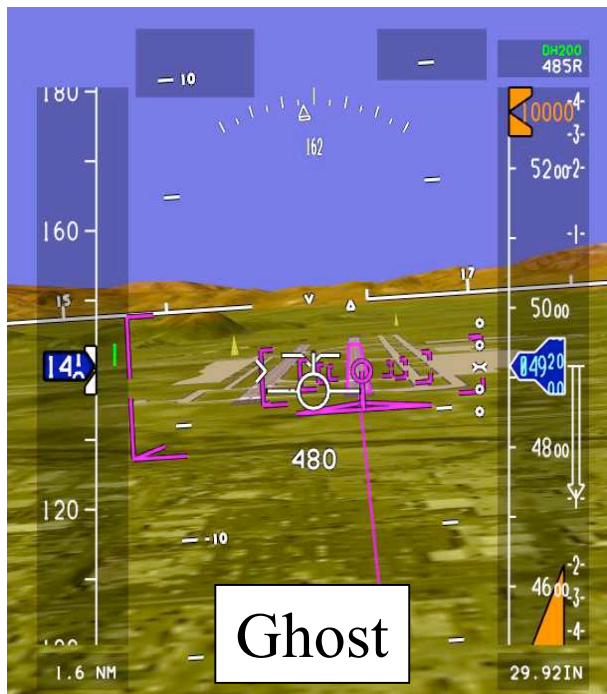
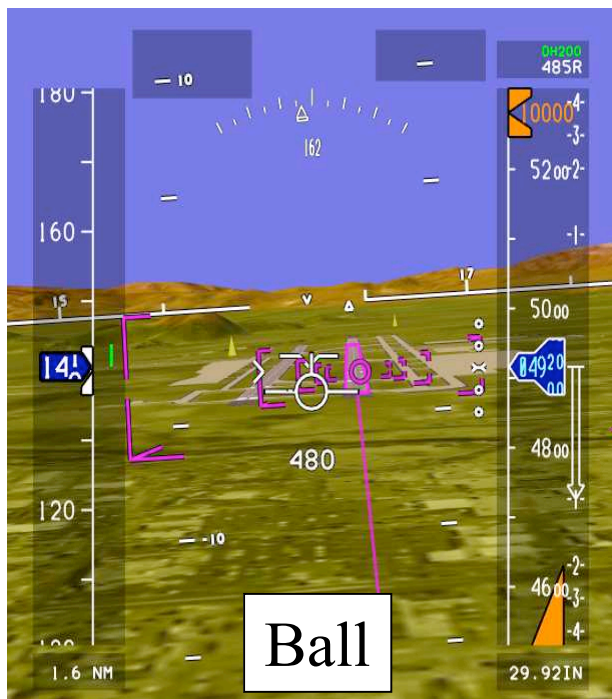
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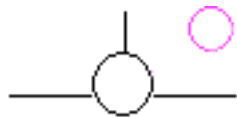
- Vertical and Lateral Deviation Raw Data Indicators
 - Deviation Scale
 - Center, +/- 2 Dots
 - Path Deviation Indicator
 - “Dogbones”
 - Angular Deviation Indicator
 - Glideslope and Localizer Deviation

Vertical Deviation Raw Data Example

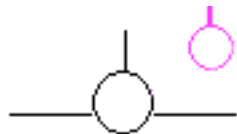




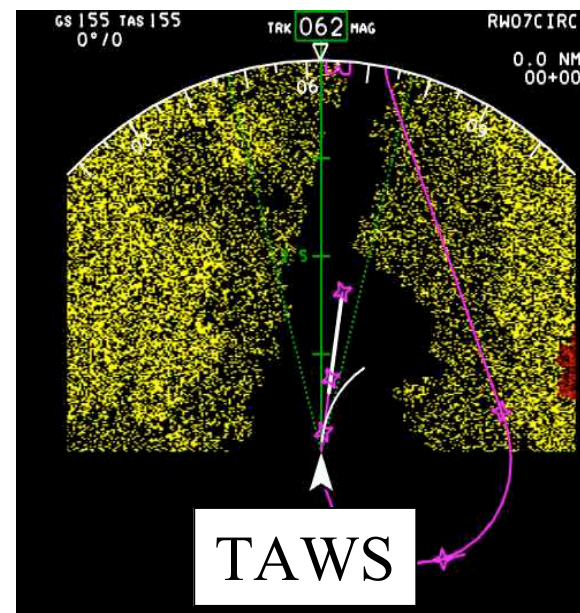
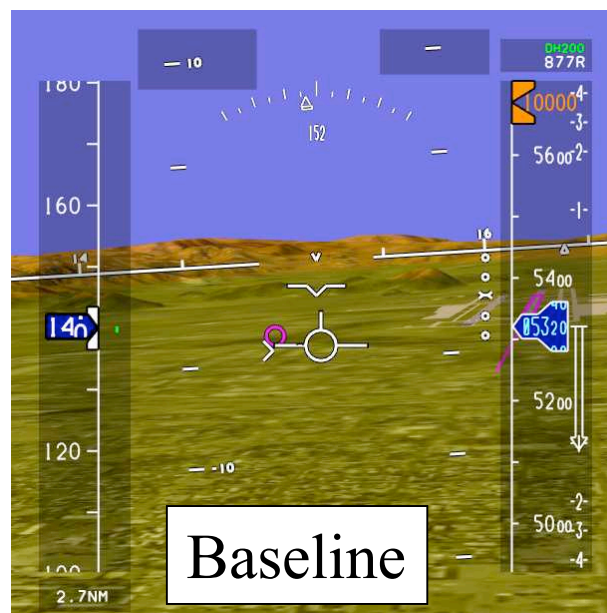
Ghost



Ball



Tadpole



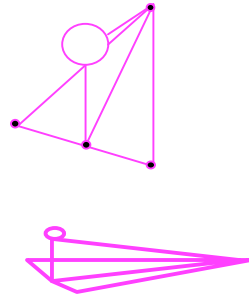


Guidance Symbology Concepts

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Ghost Aircraft (Pursuit Guidance)



- Aircraft Stick Figure, Drawn with 3D Perspective, nominally 15 Seconds Ahead of Own-Ship
- Provides Pitch and Roll Command to Tunnel Center
- Flies Down Center of Turn, Except in Turns

Tadpole (Pursuit Guidance)

Commanded Course Change



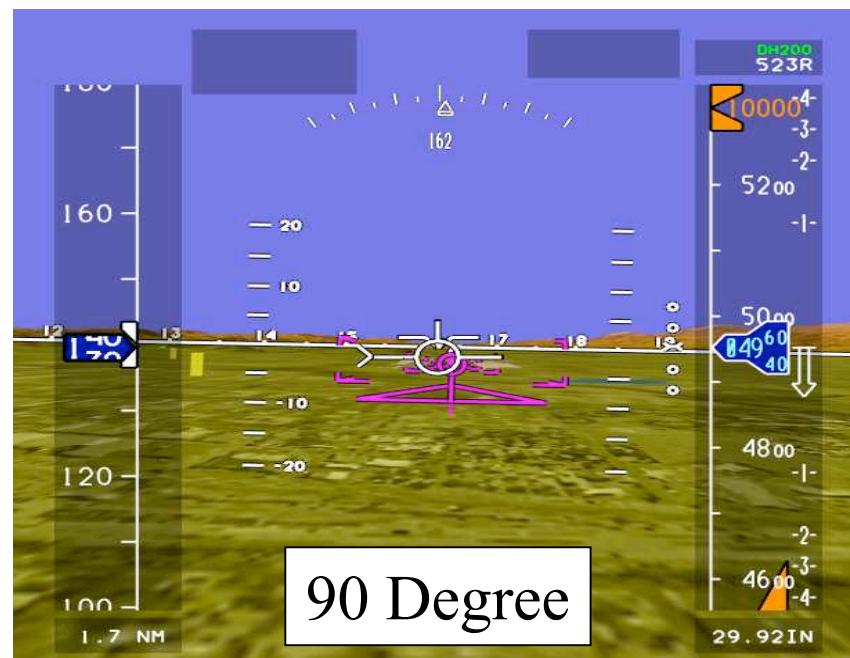
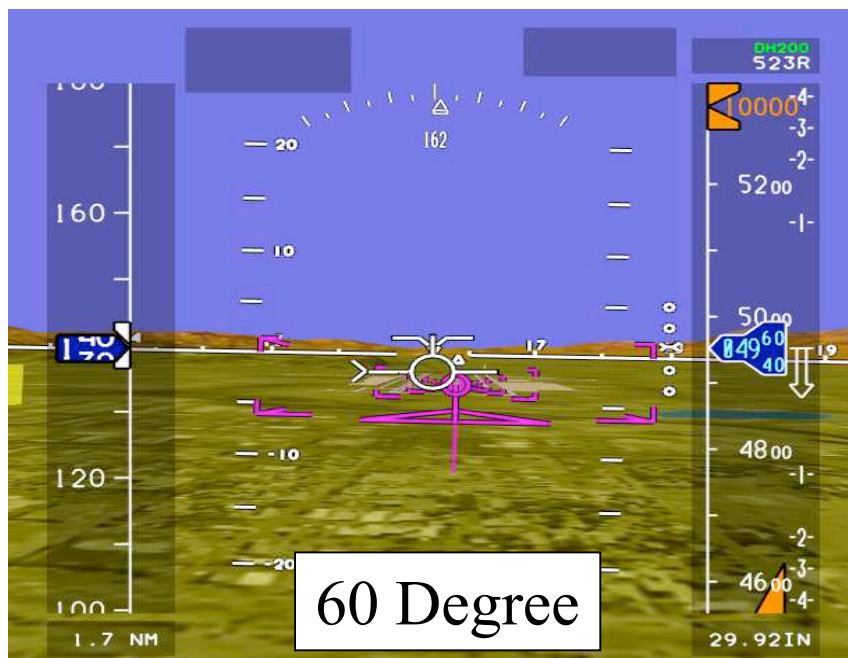
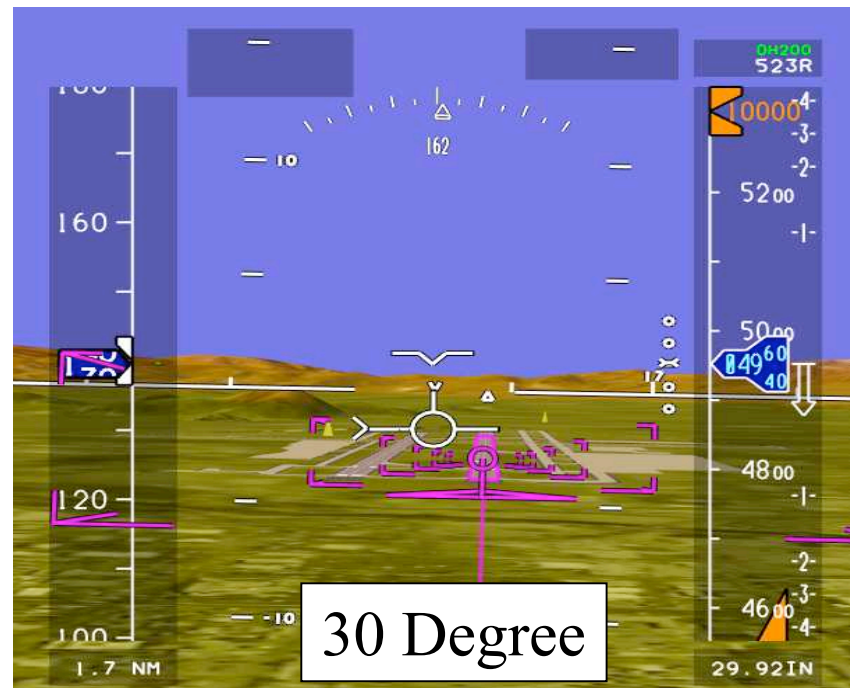
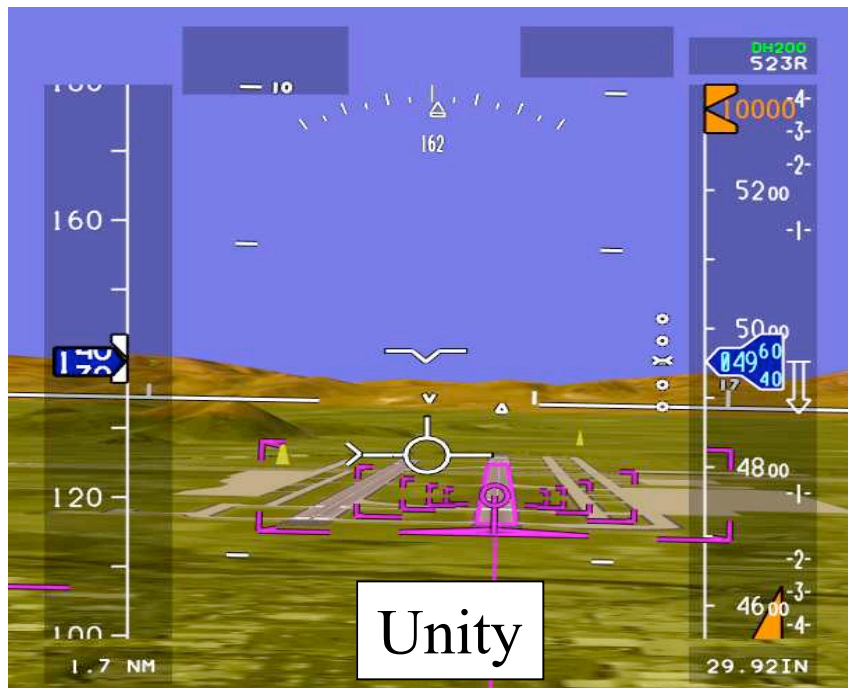
- Uses Same Pursuit Guidance Method as Ghost Aircraft without 3D Aircraft Stick Figure
- Flies Down Center of Turn, Except in Turns
- Tadpole Angle Shows Direction of Commanded Turns

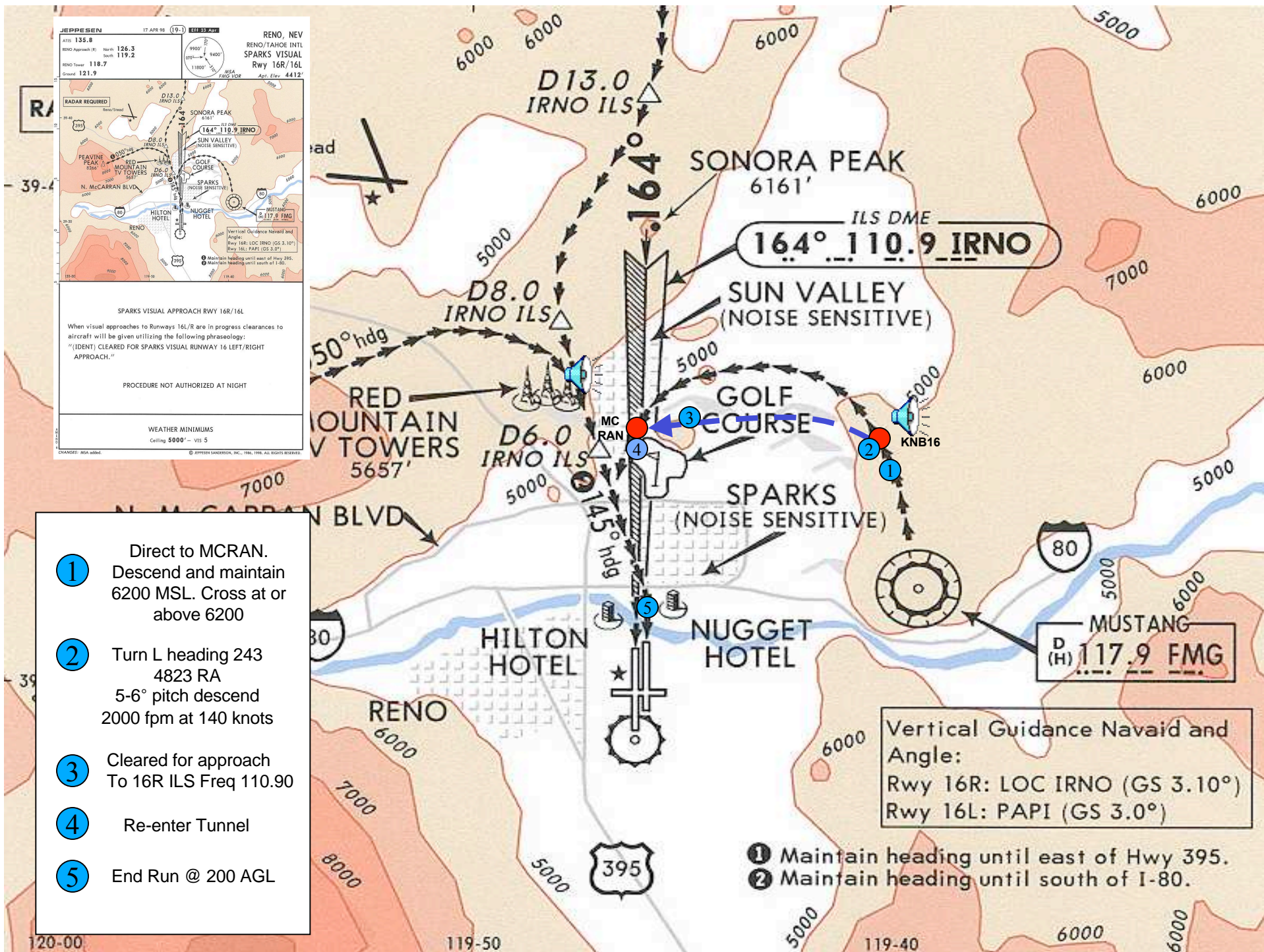
Ball

(pursuit guidance)



- Same as Ghost and Tadpole





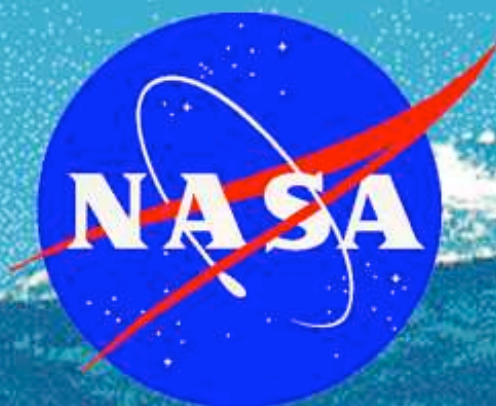


Tunnel Concepts During Sparks 16R Approach

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Dynamic Tunnel
&
Ghost Symbology



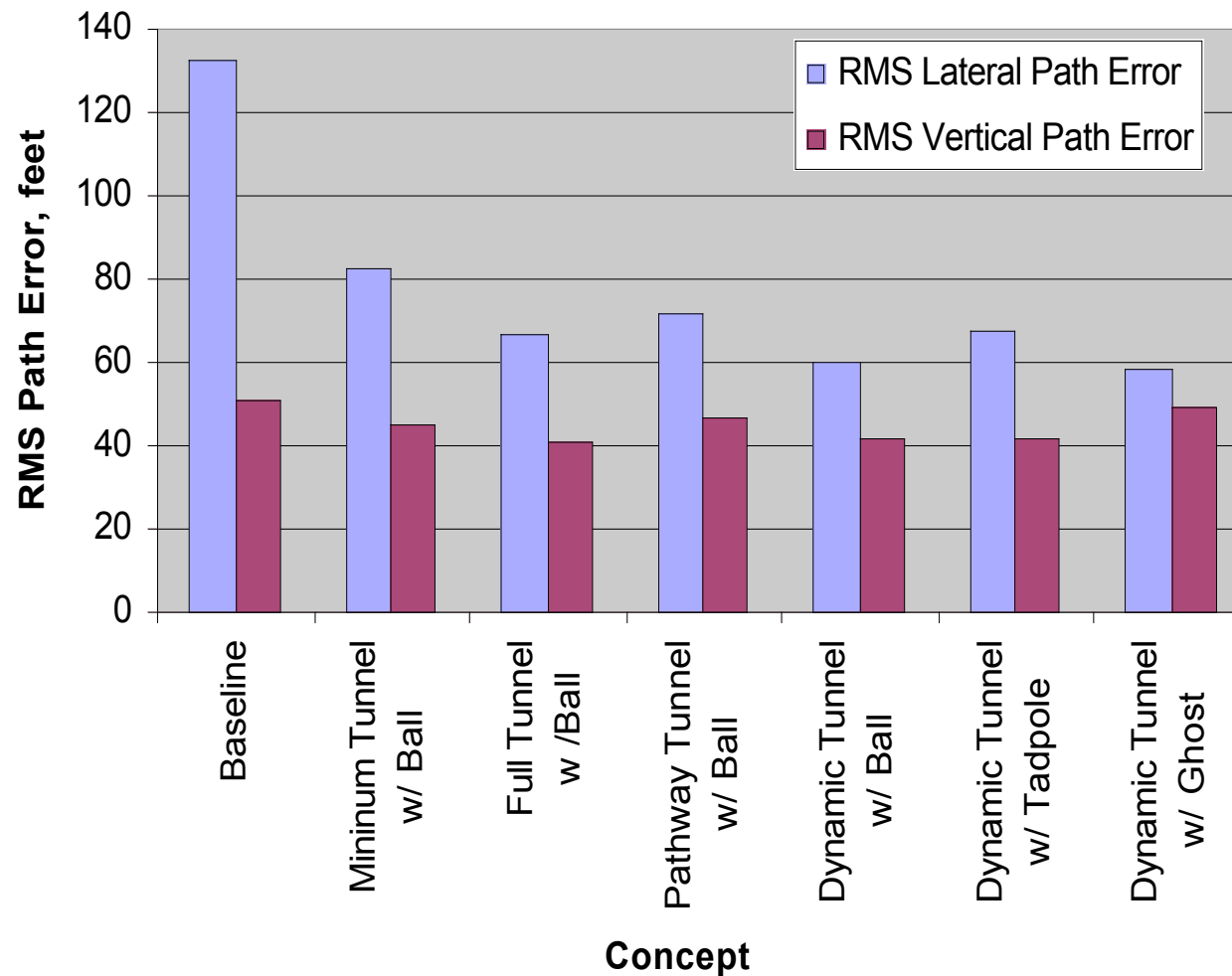
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Performance Results



Tunnel Concept RMS Error

Approach RMS Path Error



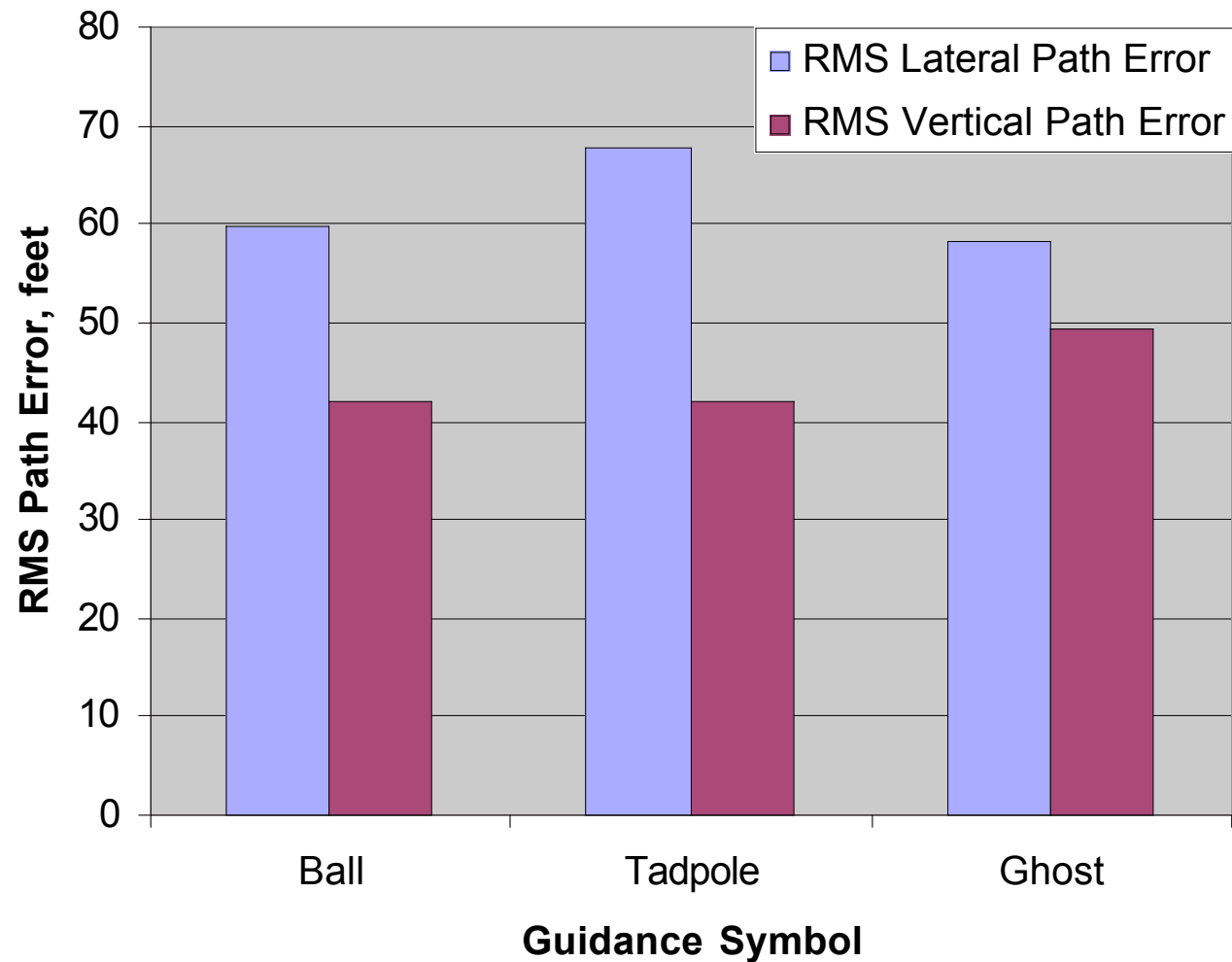


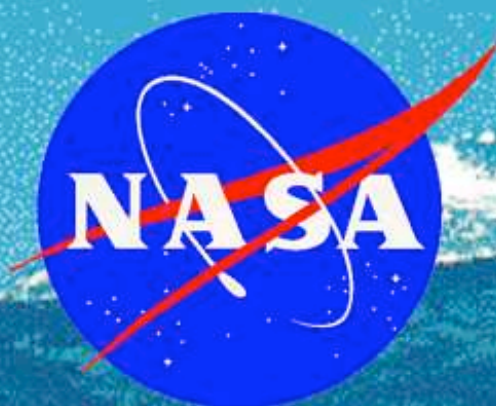
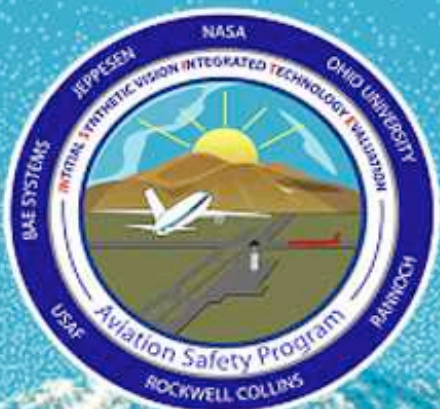
Guidance Concept RMS Error

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Approach RMS Path Error





PRECISE

Run Questionnaire Results



Post-Run Questionnaires

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	Workload Estimate
1	Nothing To Do; No System Demands
2	Light Activity; Minimum Demands
3	Moderate Activity - Easily Managed; Considerable Spare Time
4	Busy - Challenging but Manageable; Adequate Time Available
5	Very Busy - Demanding To Manage; Adequate Time Available
6	Extremely Busy - Very Difficult; Non - Essential Tasks Postponed
7	Overloaded - System Unmanageable; Essential Tasks Undone; Unsafe

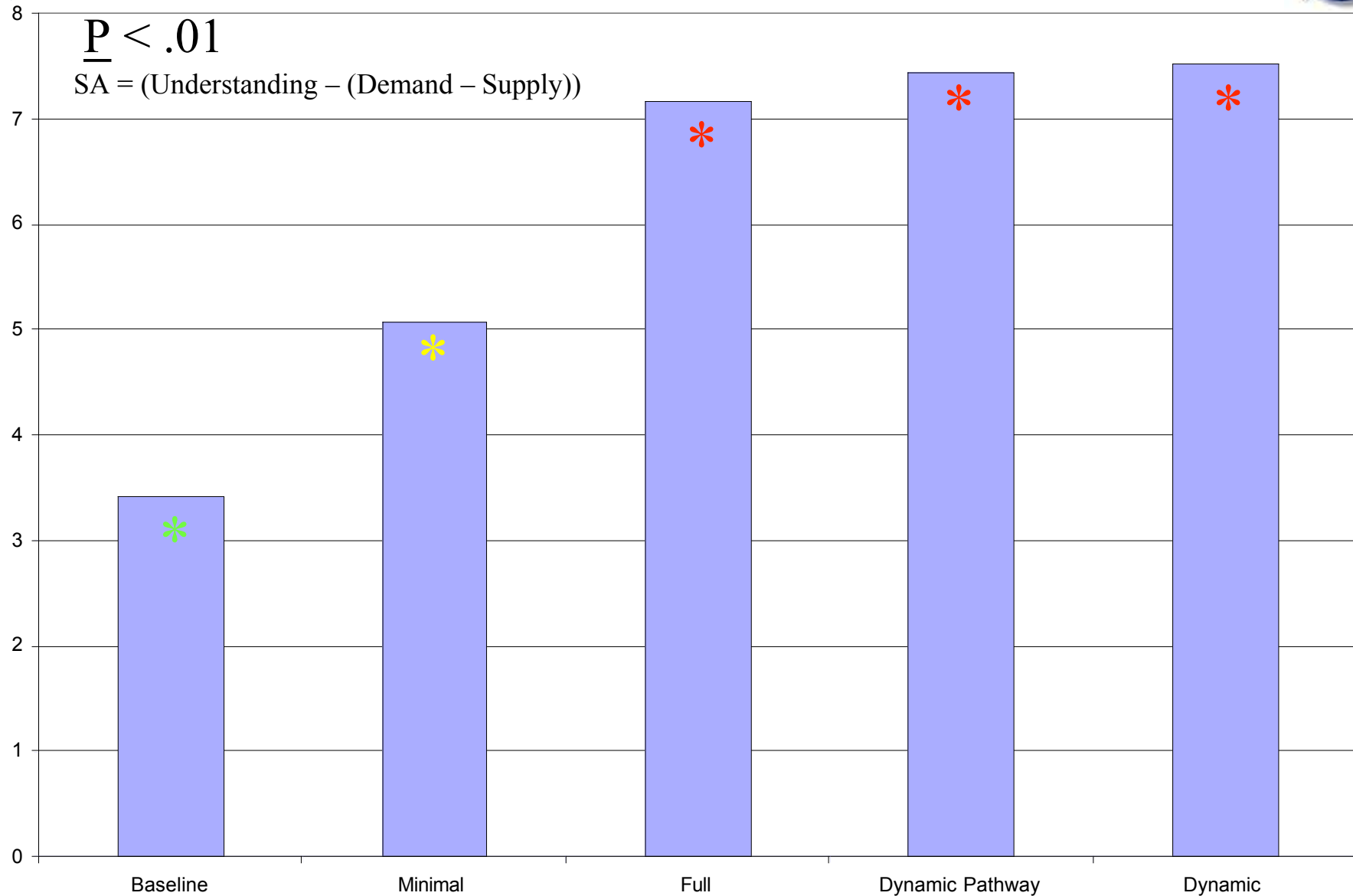
Situation Awareness Ratings	Low High						
	1	2	3	4	5	6	7
SART #1 - <u>Demand on Attentional Resources</u> How Much Demand Was Placed On Attention Due To Complexity And Variability Of The Task?							
SART #2 - Supply of Attentional Resources : How Much Spare Attention And Mental Ability Was Available To Accomplish The Task?							
SART #3 - Understanding : What Was The Level Of Understanding Of Information And Familiarity Of The Situation?							

Post -Run Questions	Low High						
	1	2	3	4	5	6	7
Q. 1: As I Performed The Task, My Awareness Of Where I Was In The Tunnel Was _____.							
Q. 2: As I Performed The Task, My Awareness Of Upcoming Turns Using the Tunnel Was _____.							
Q. 3: As I Performed The Task, My Level Of Flight Path Control And Performance Was _____.							
Q. 4: As I Performed the Task, My Ability to Intercept the Path and Re-Enter the Tunnel Was _____.							
Q. 5: As I Performed the Task, My Ability to Anticipate Flight Path Changes Using the Guidance Symbol Was _____.							
Q. 6: As I Performed The Task, My Awareness of Terrain Features and Obstacles Was _____.							



SART Ratings

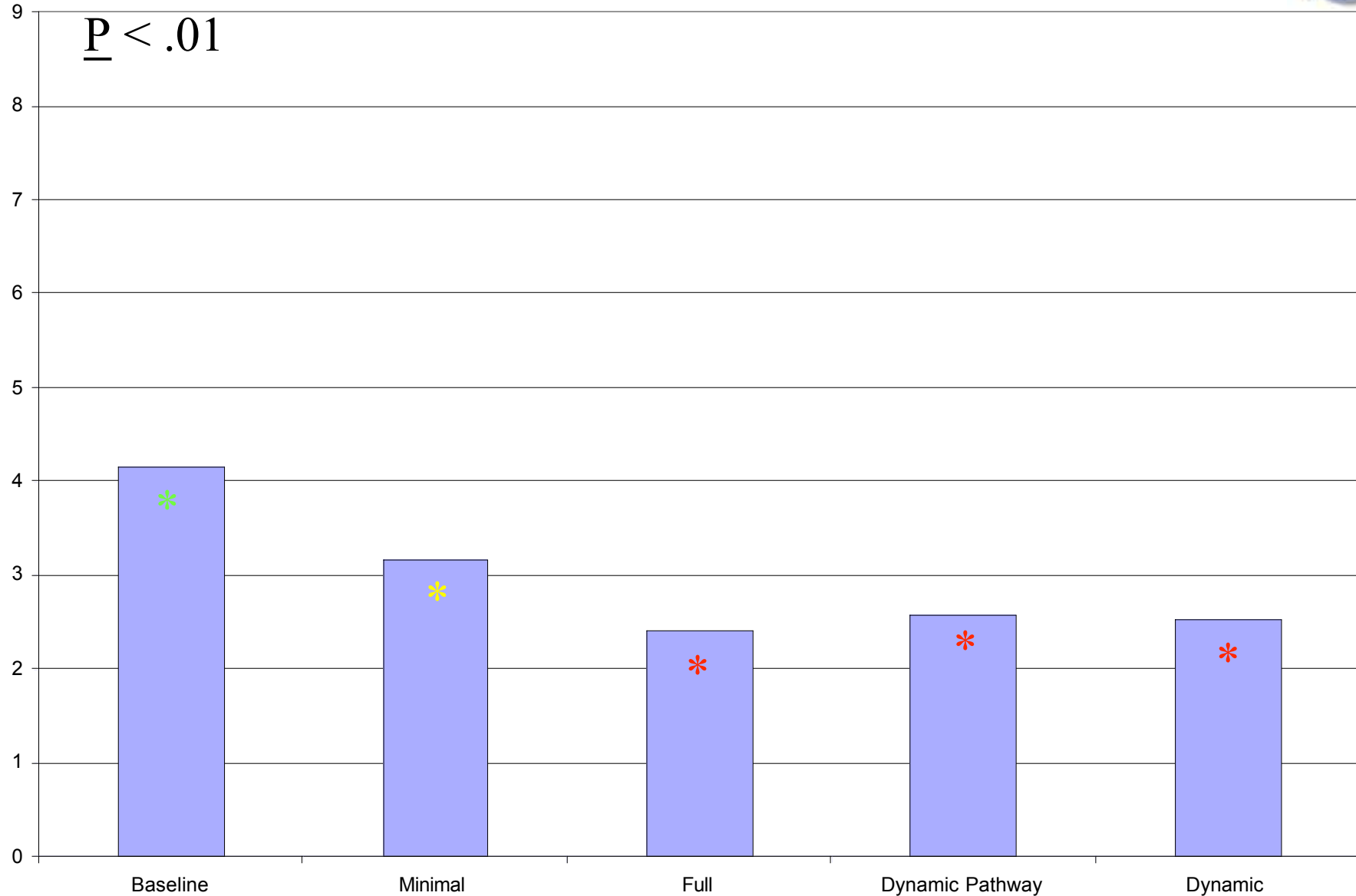
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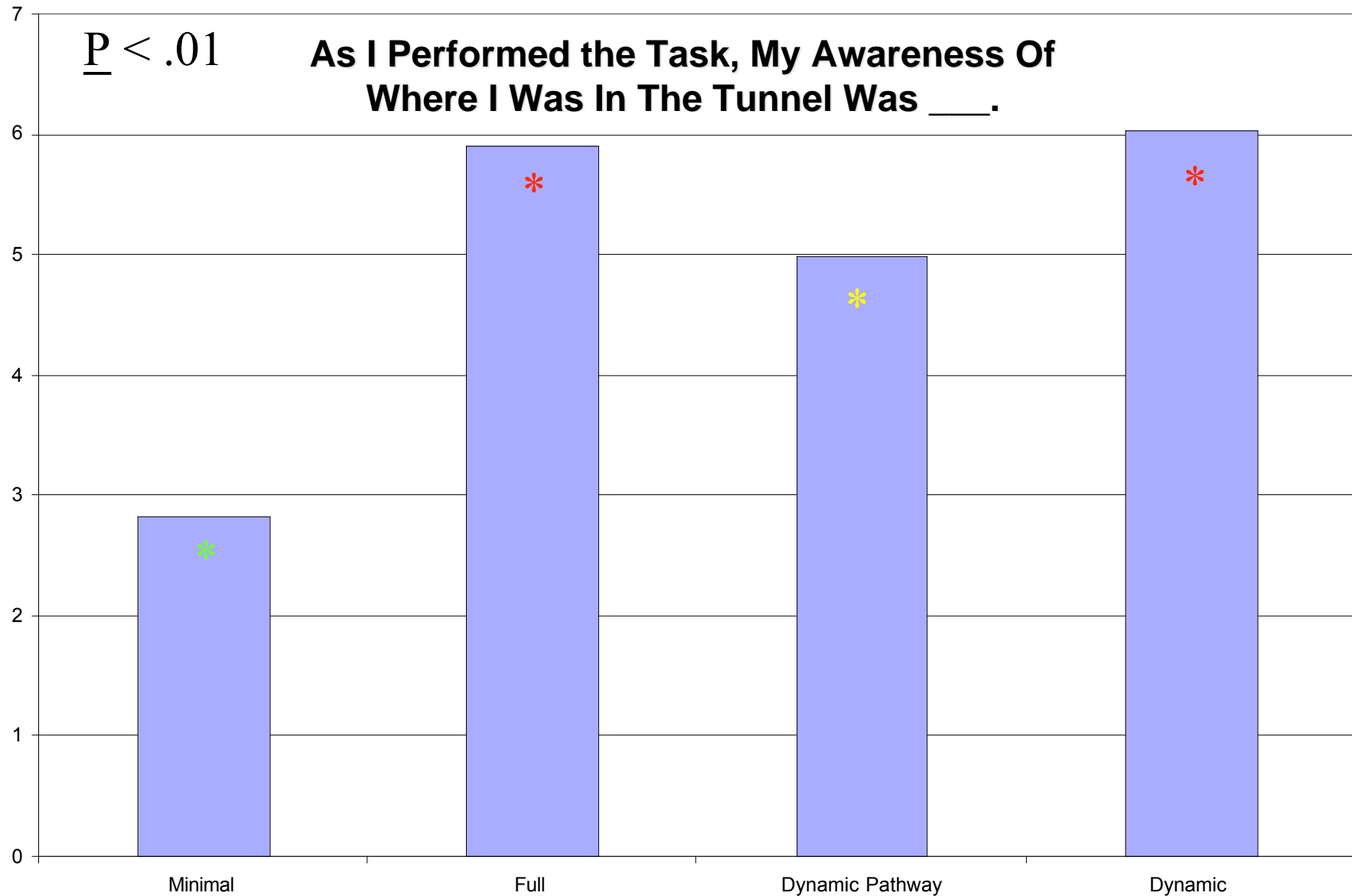
Mental Workload Ratings

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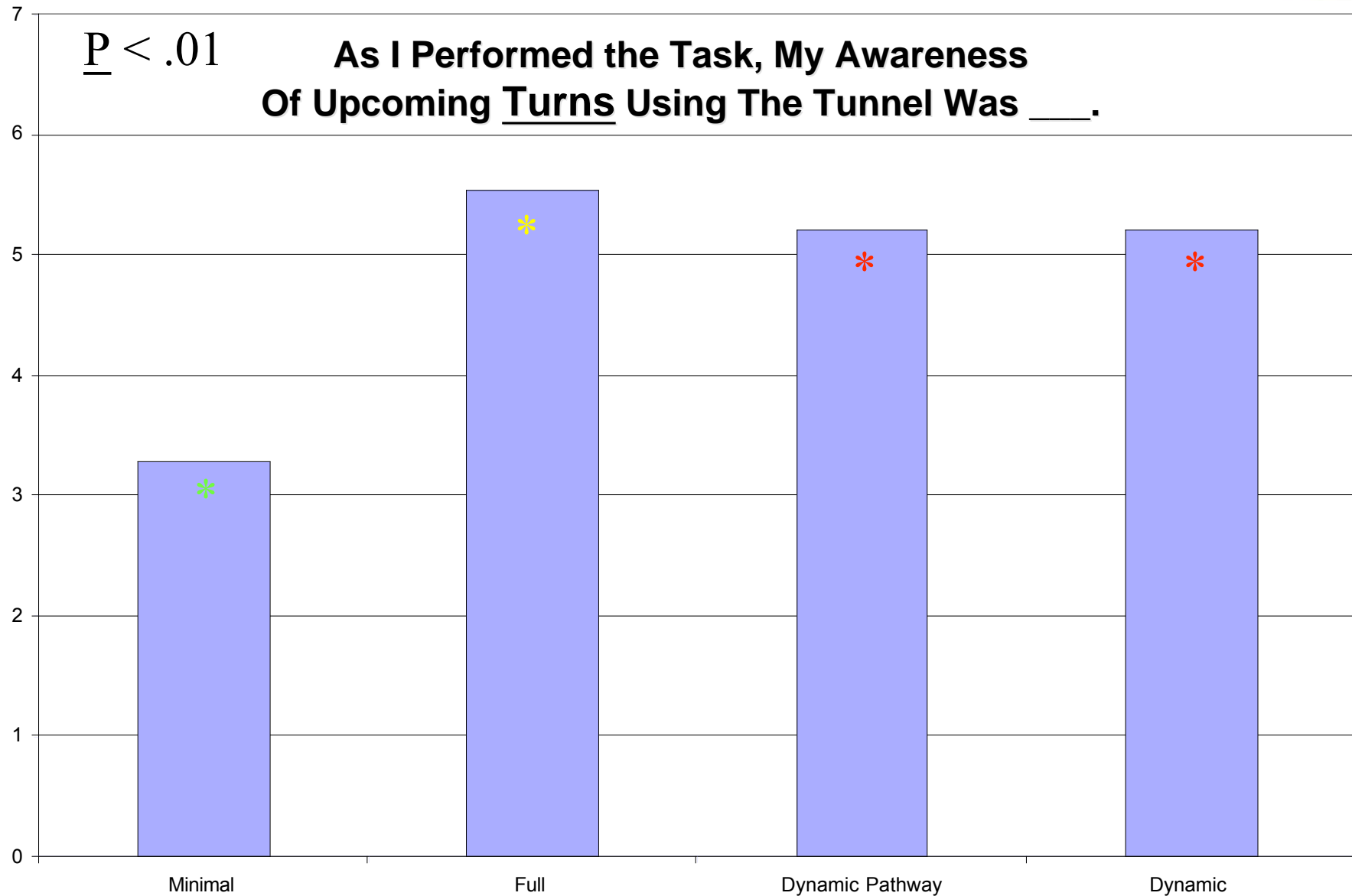
Post-Run Question





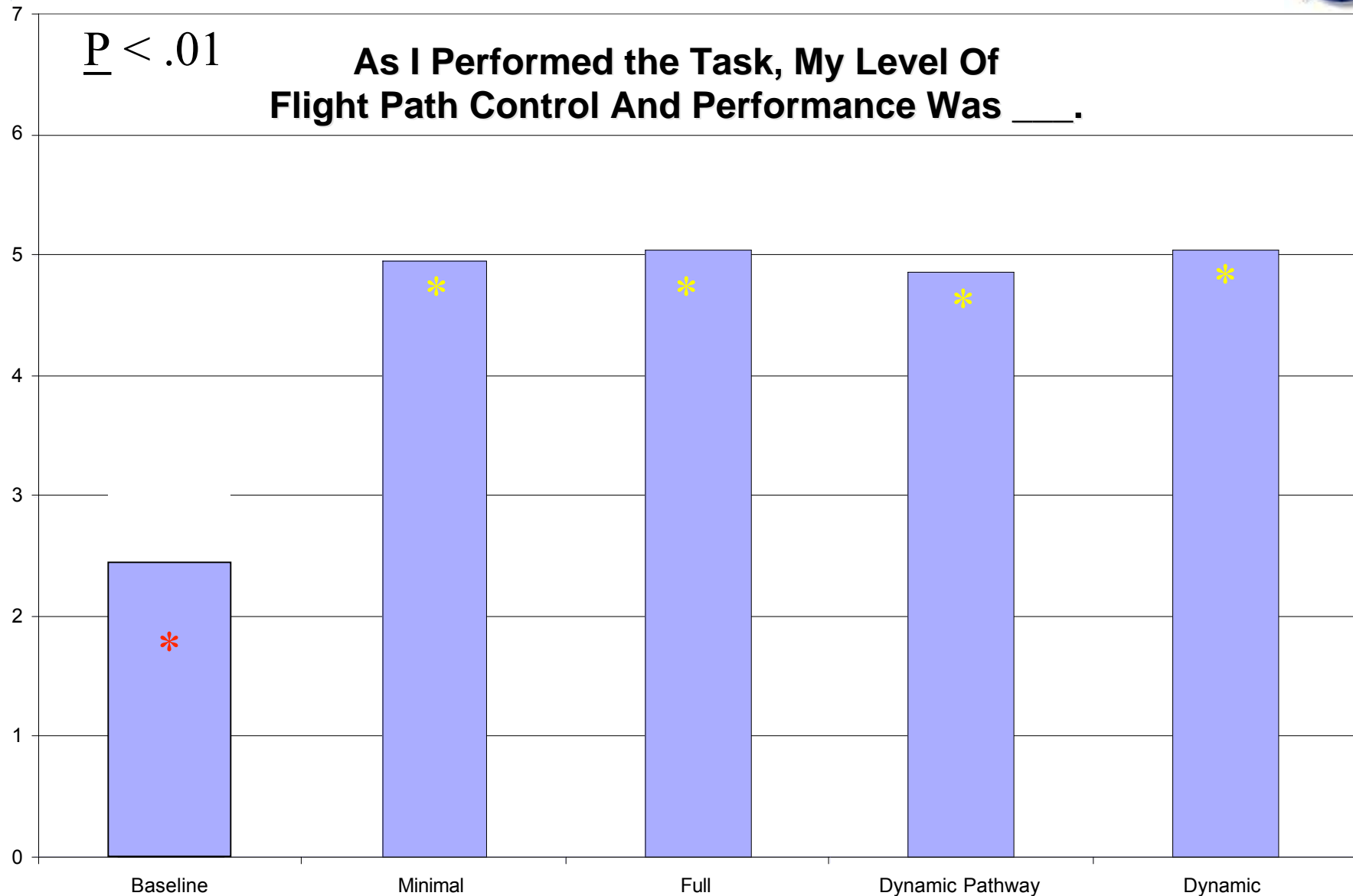
Post-Run Question

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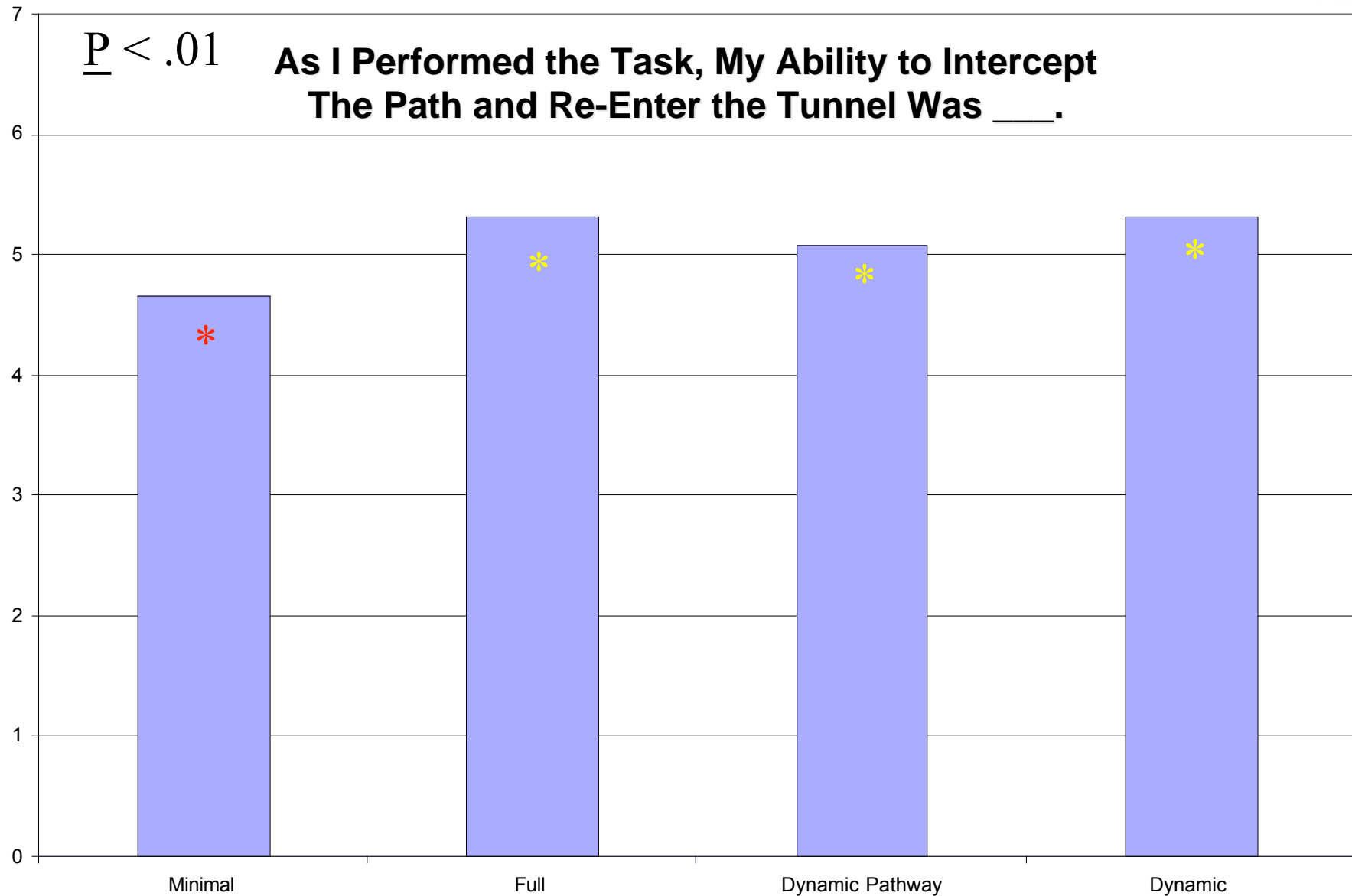
Post-Run Question





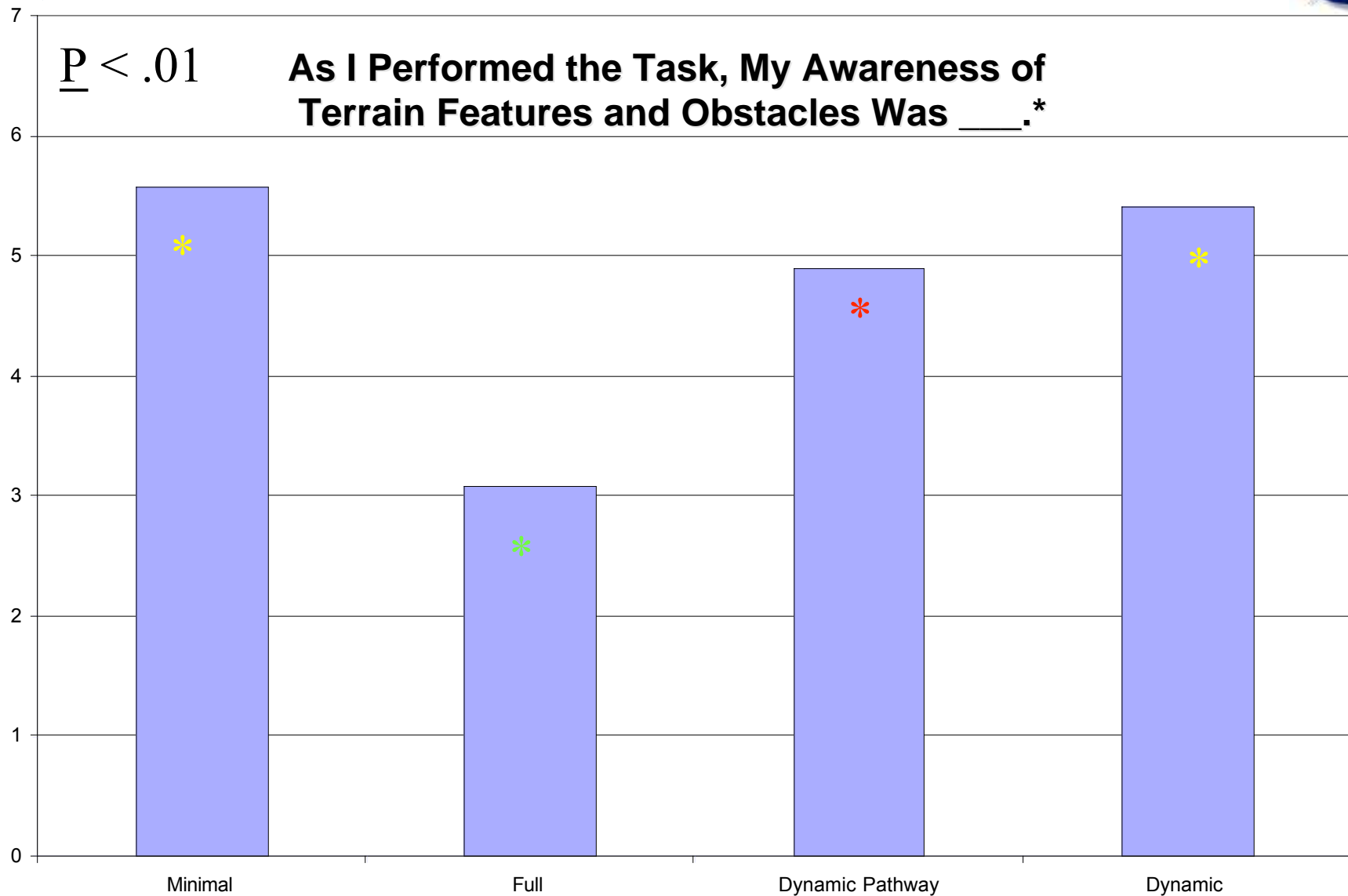
Post-Run Question

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Post-Run Question

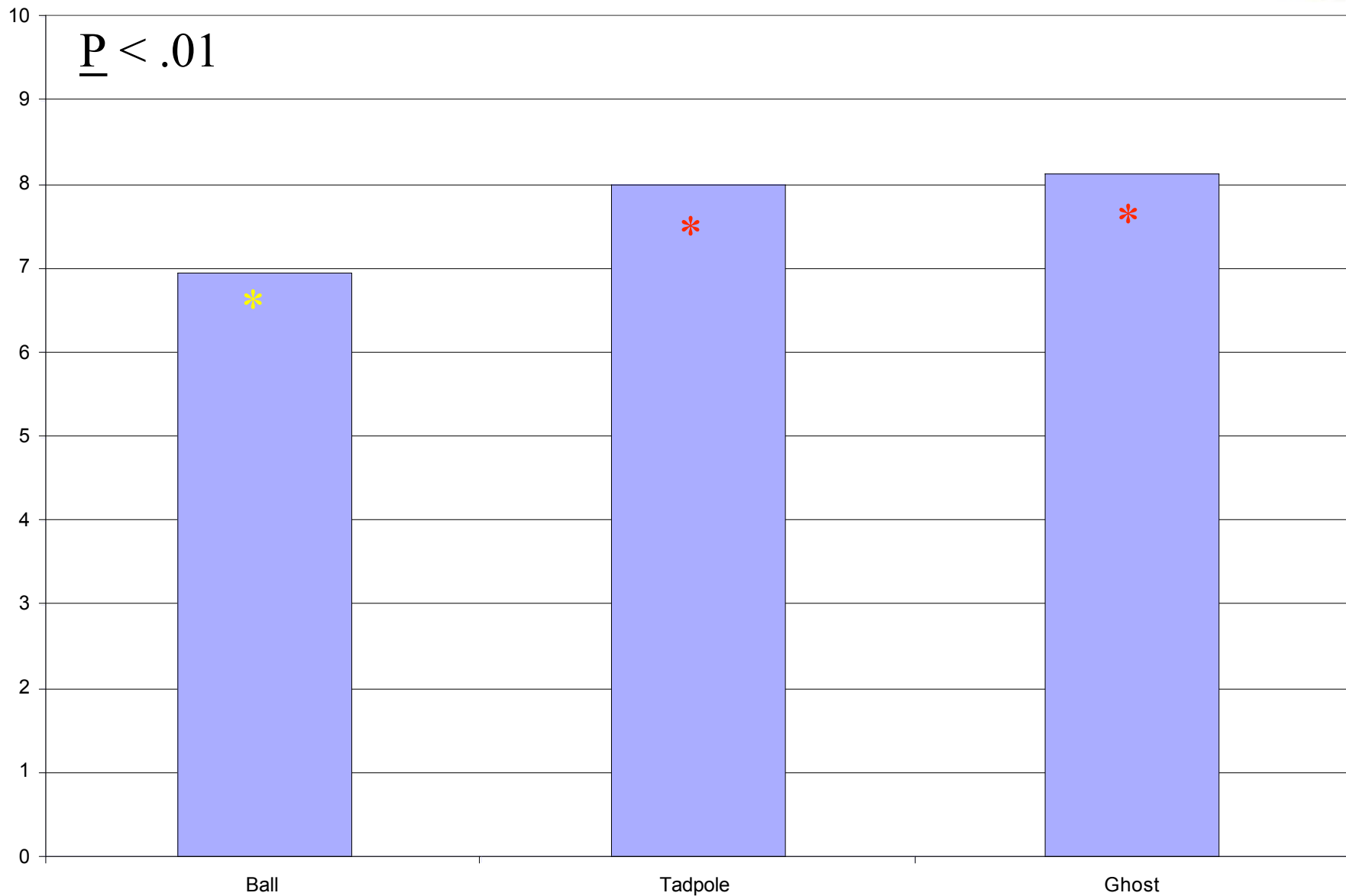


* Pilots were briefed that question concerned clutter versus information



SART Ratings for Guidance Concepts

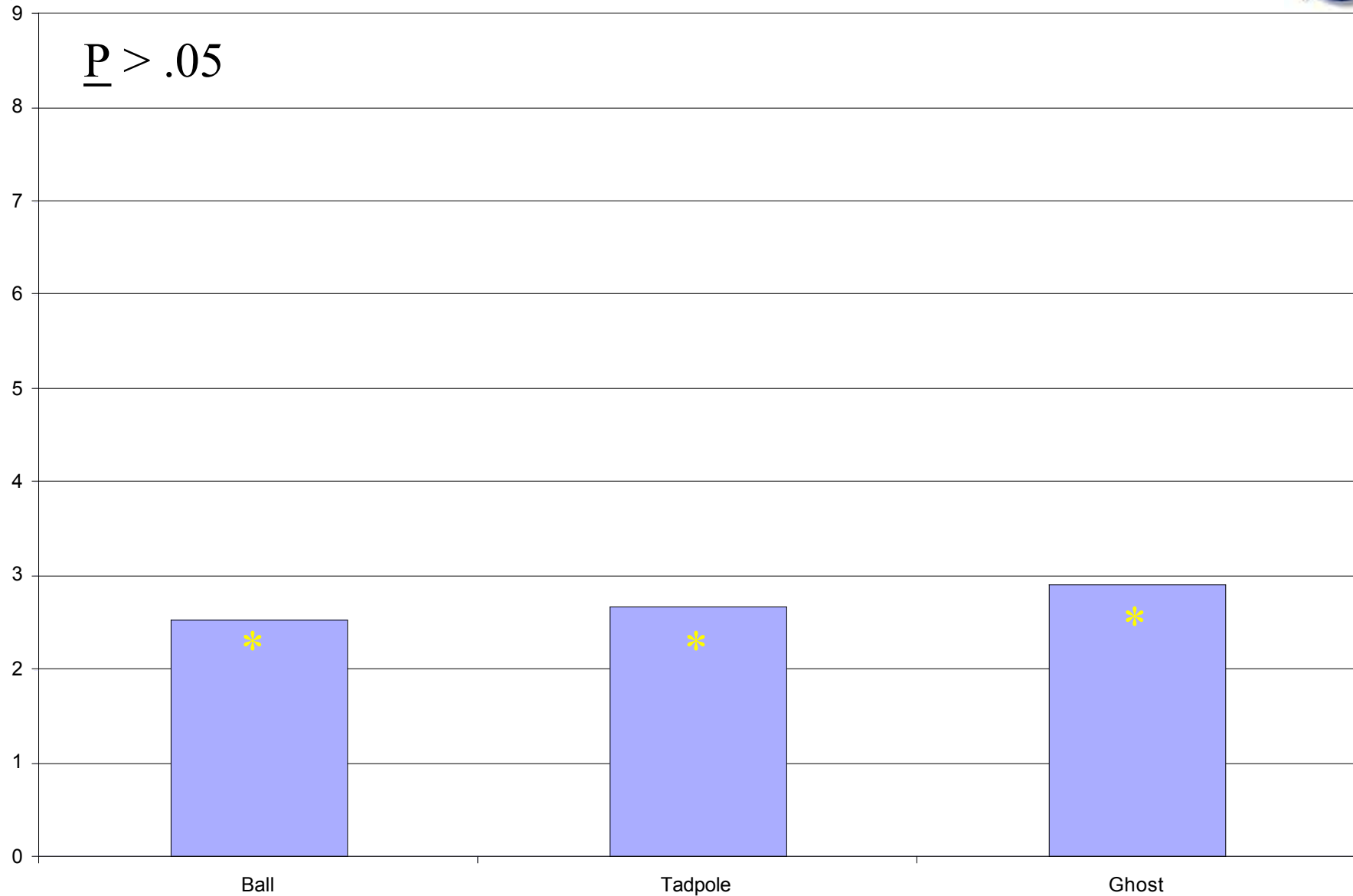
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Workload Ratings for Guidance Concepts

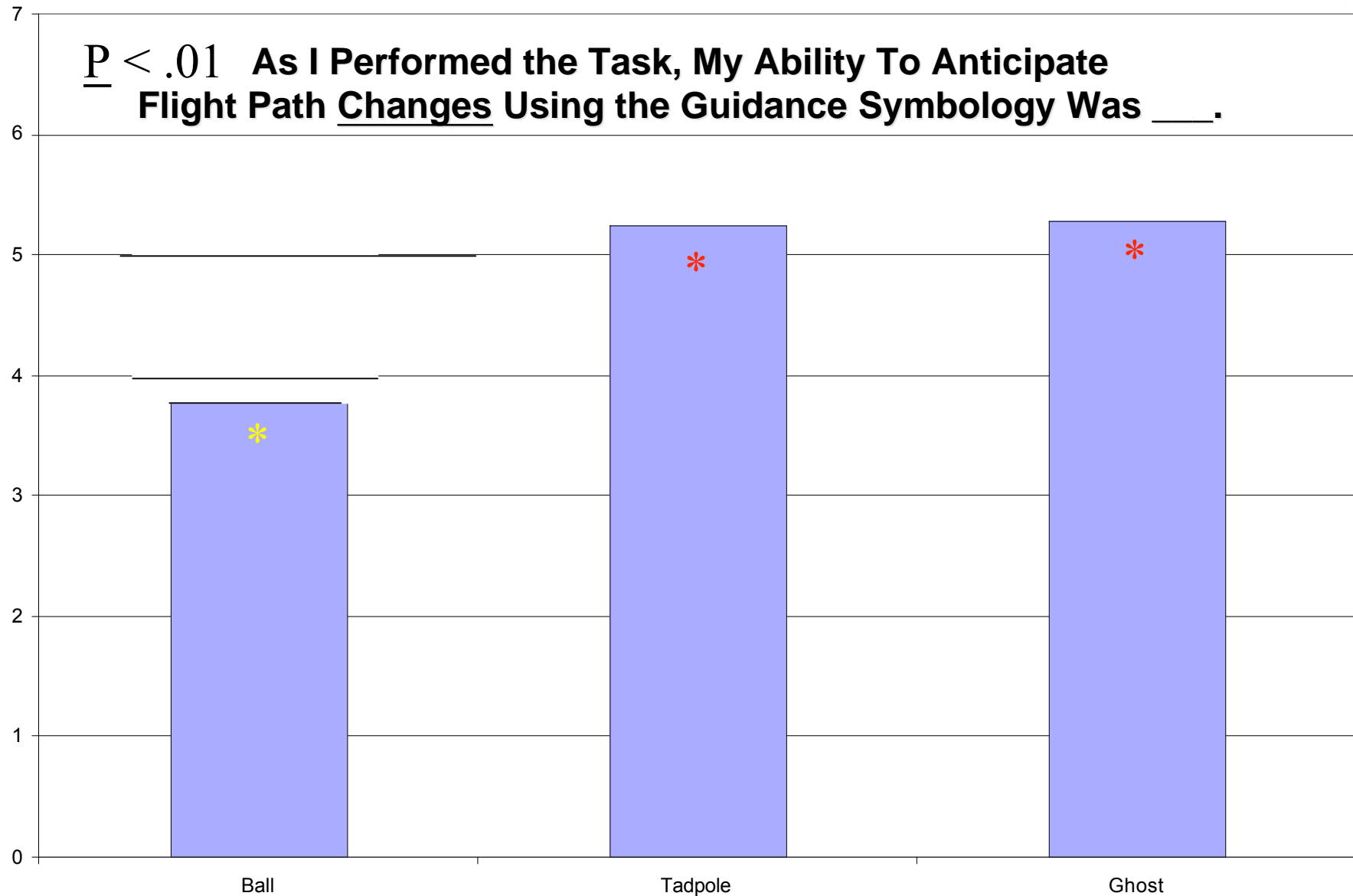
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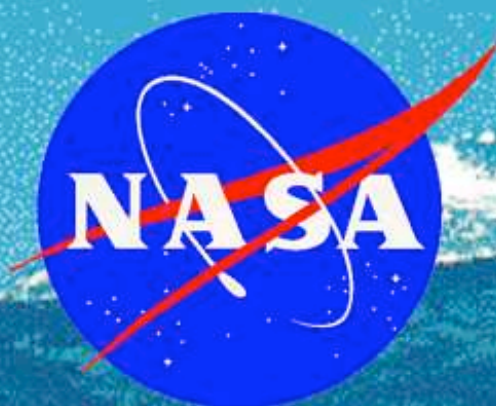
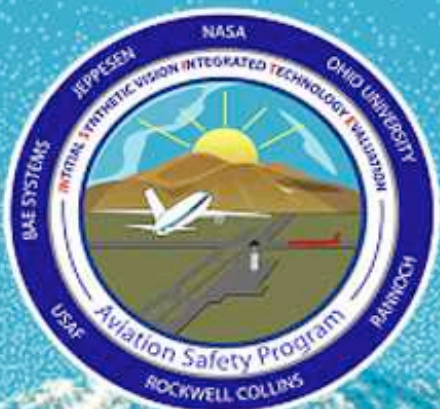




Post-Run Question

P < .01 As I Performed the Task, My Ability To Anticipate Flight Path Changes Using the Guidance Symbology Was ____.





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Semi-Structured Interview Results

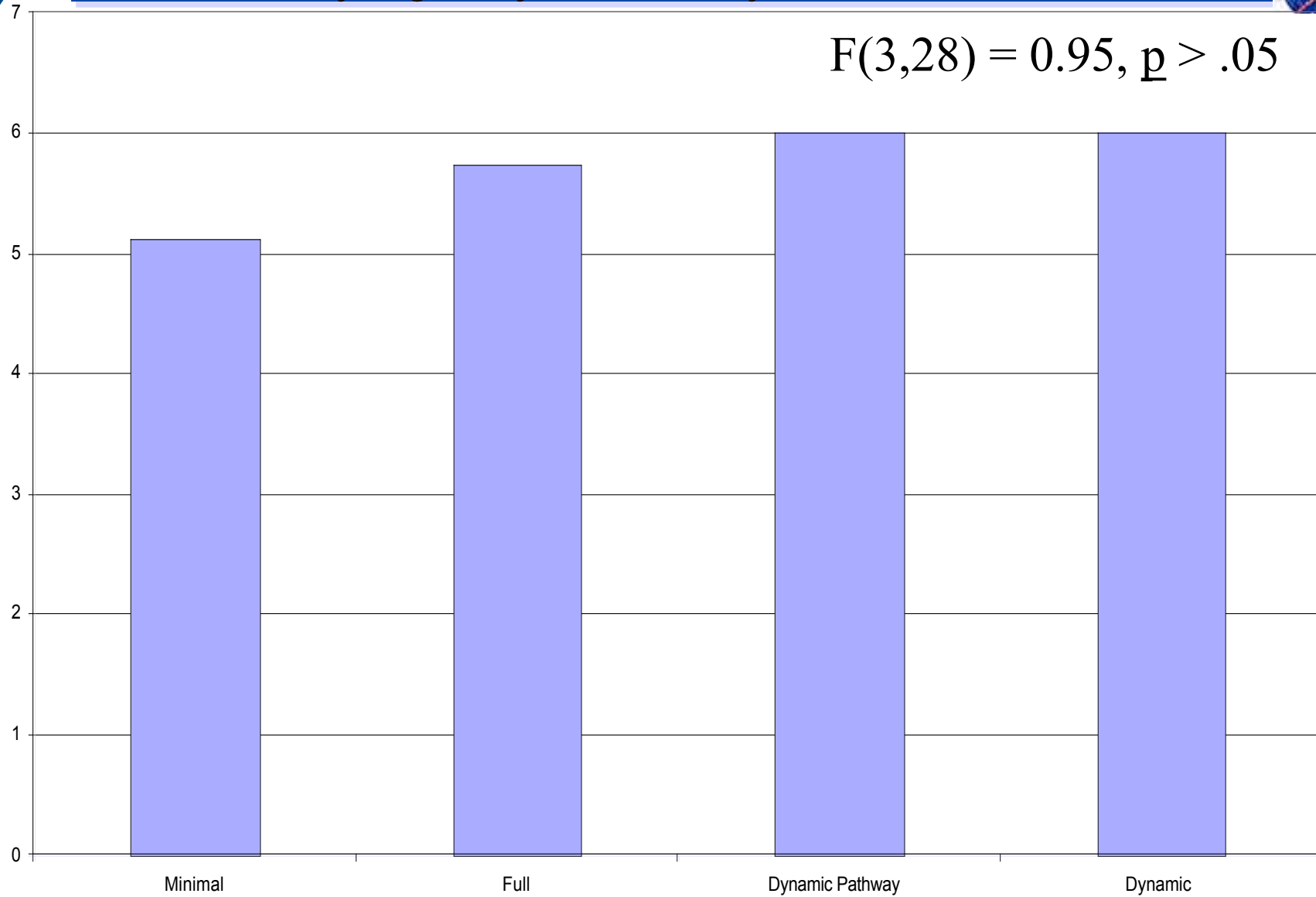


Effectiveness During Straight Path Segments

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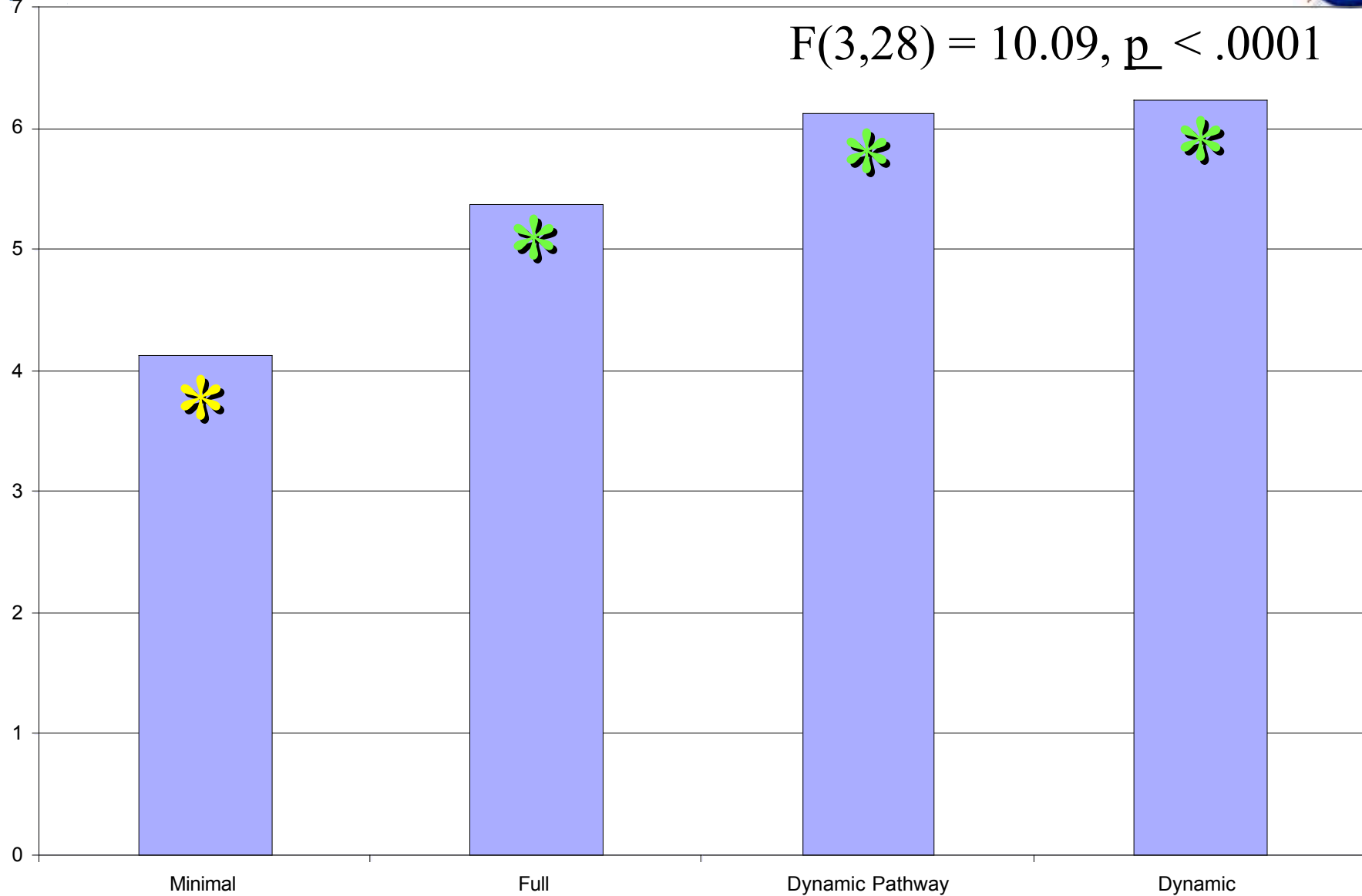
$F(3,28) = 0.95, p > .05$

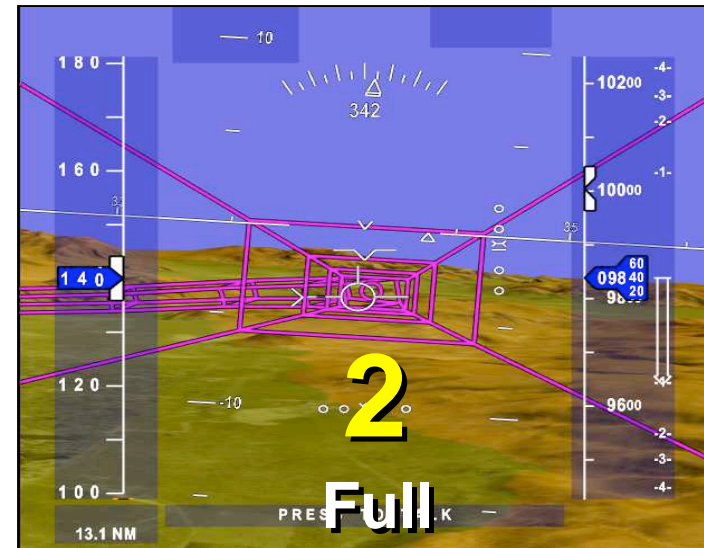




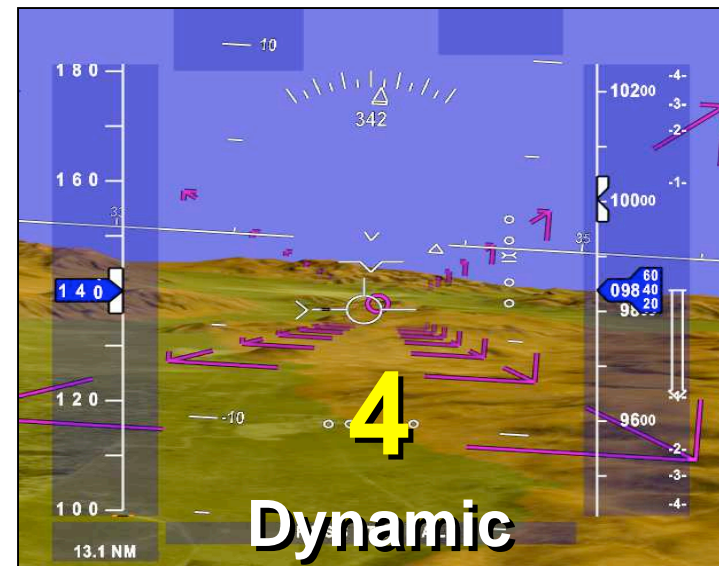
Effectiveness During Curved Path Segments

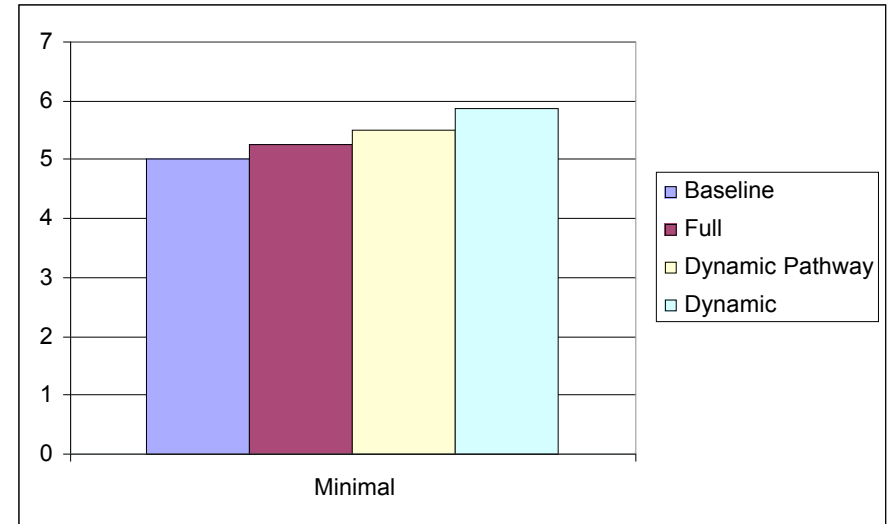
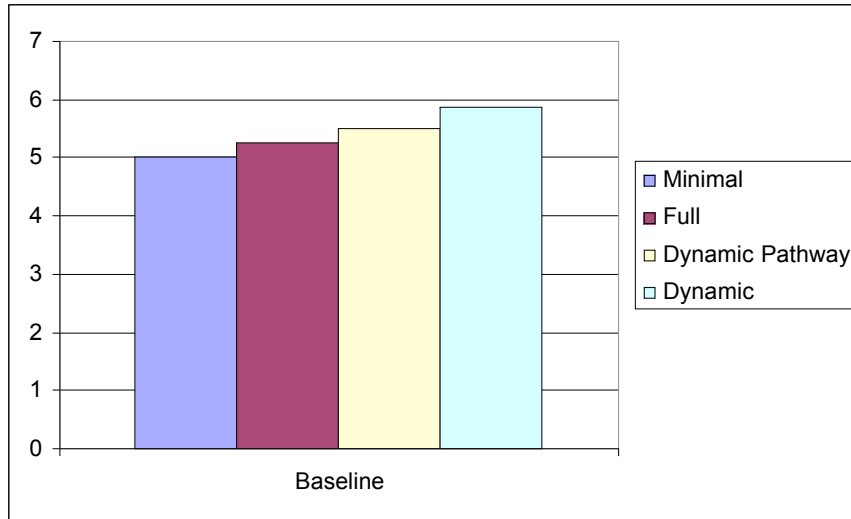
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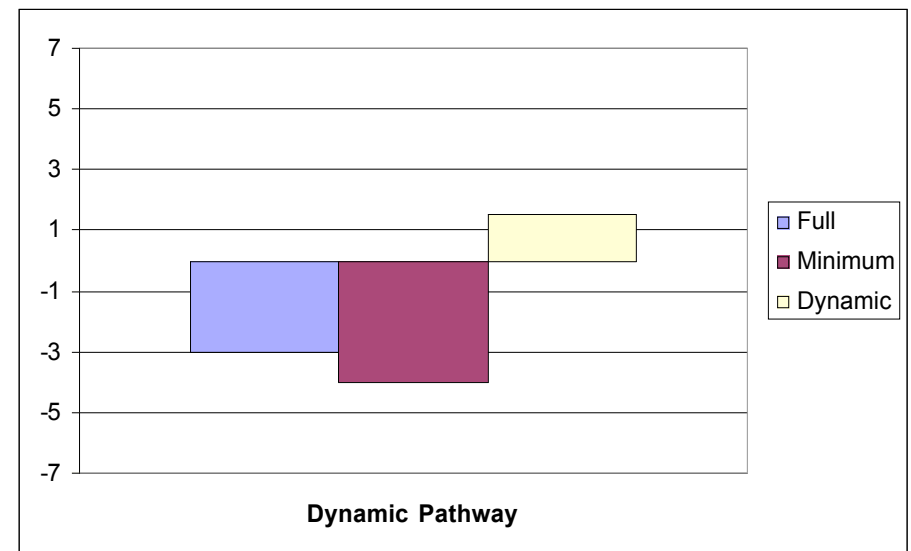
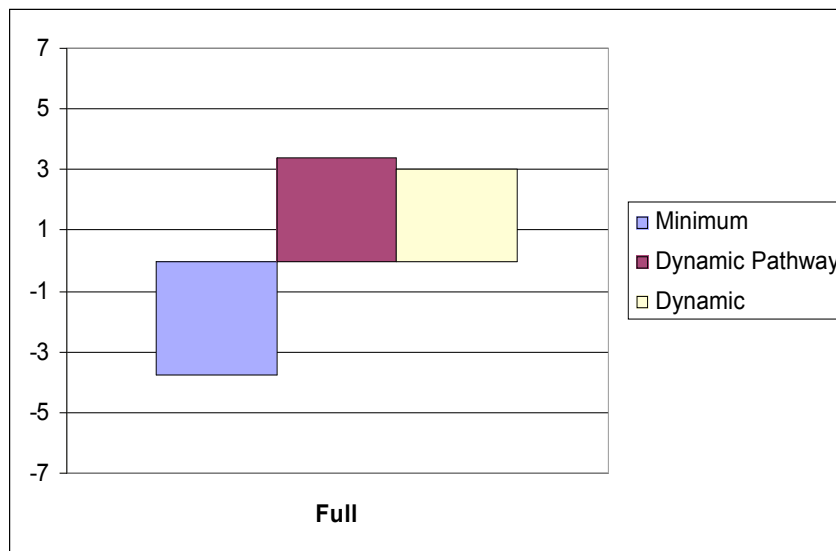


Overall Rank Ordering of Tunnels





Relative Difference in Situation Awareness Across Concepts



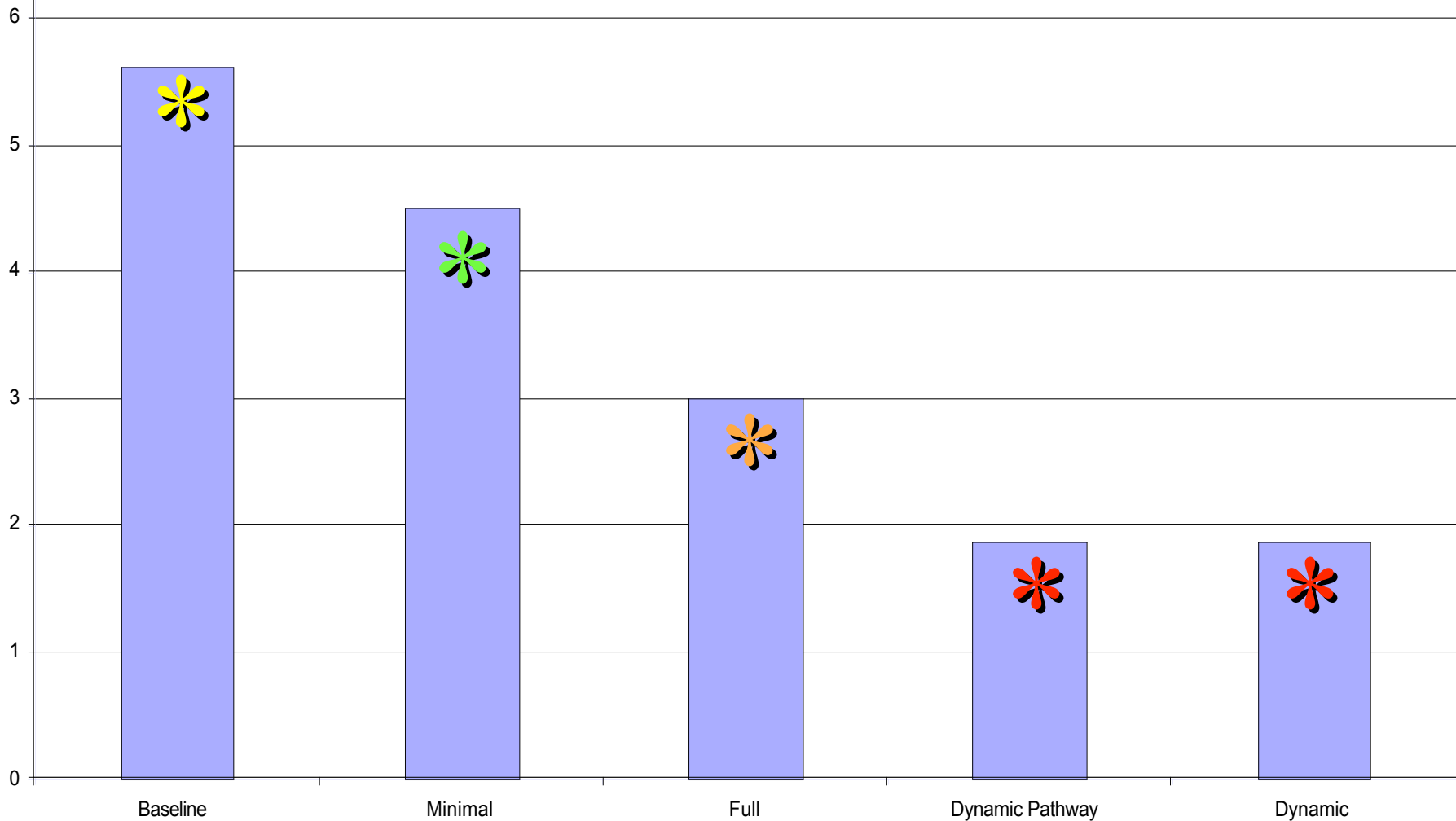


Workload Experienced During “Cut-The-Corner”

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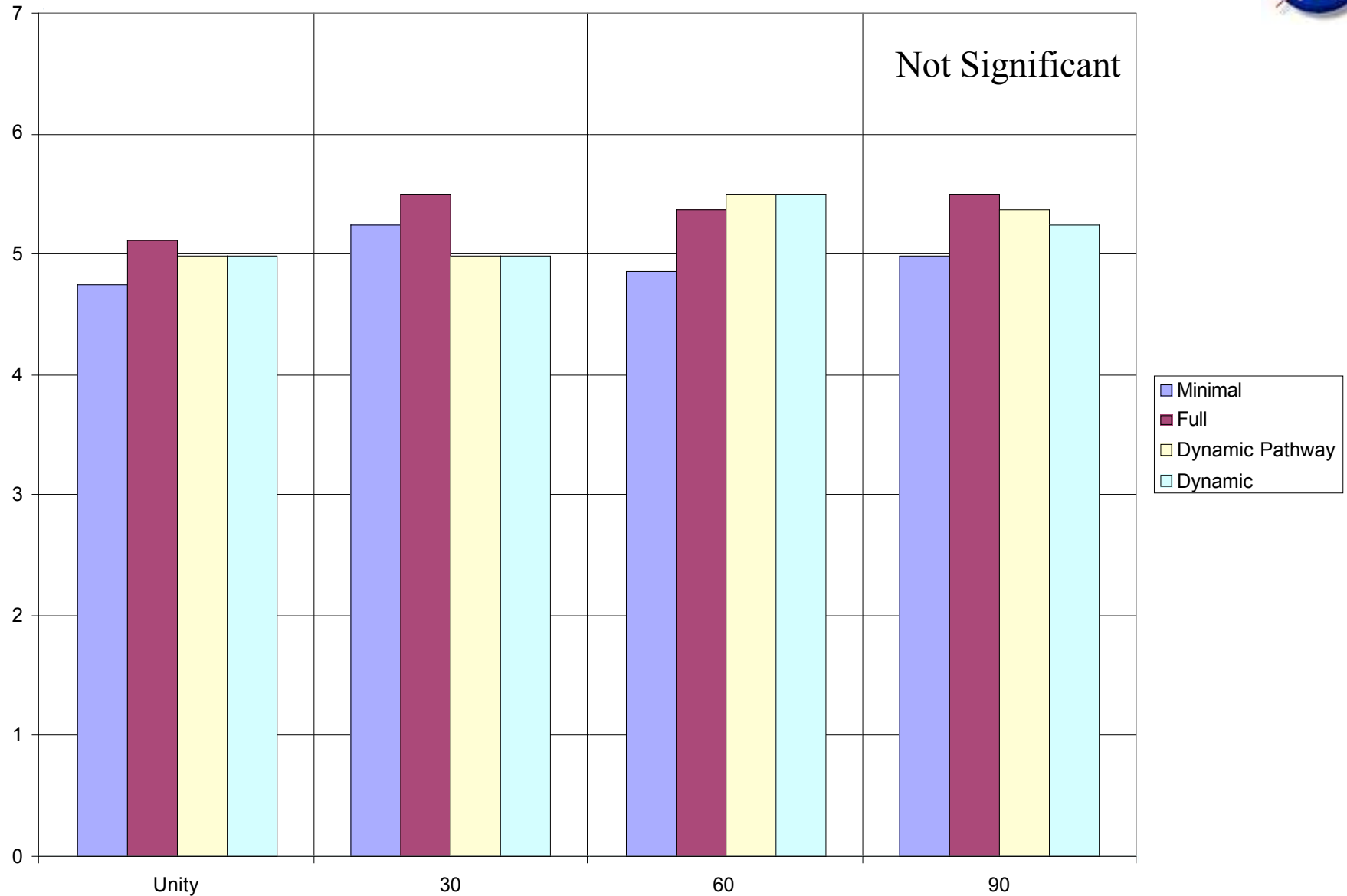
$F(3,35) = 43.56, p < .0001$





Effectiveness of FOV During Straight Segments

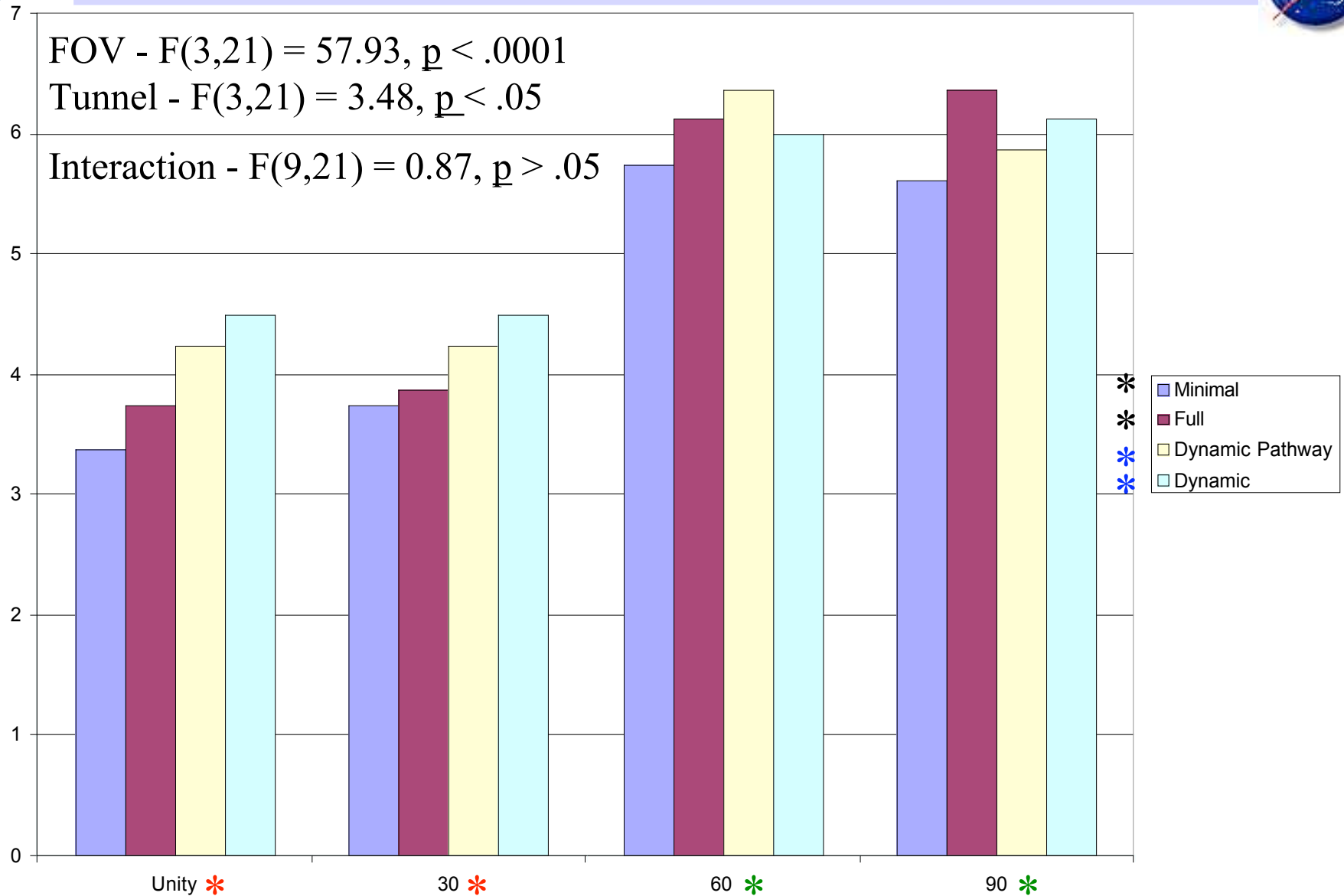
Aviation Safety Program: Synthetic Vision Systems





Effectiveness of FOV During Curved Segments

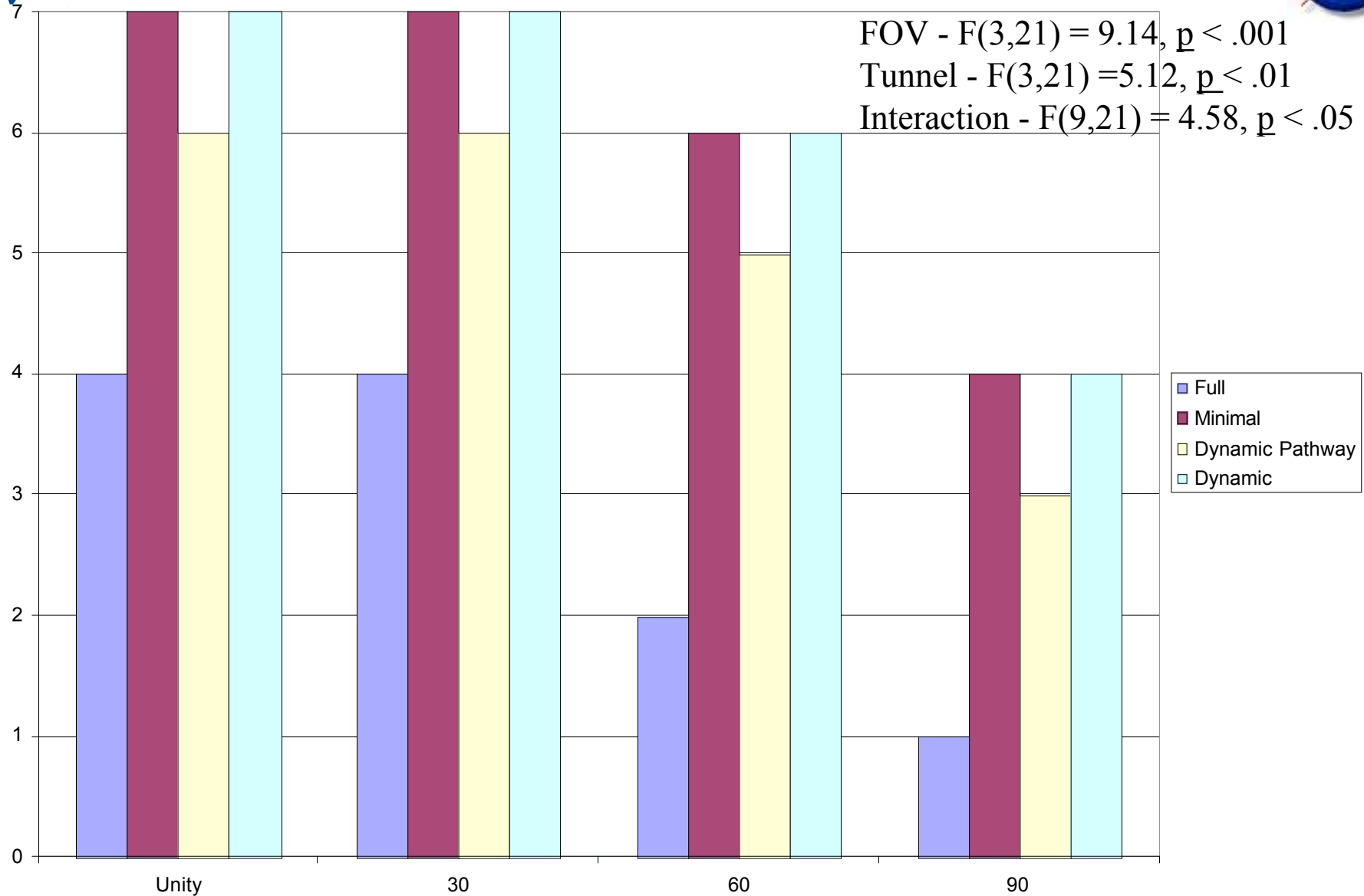
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Effectiveness of FOV During Final Approach

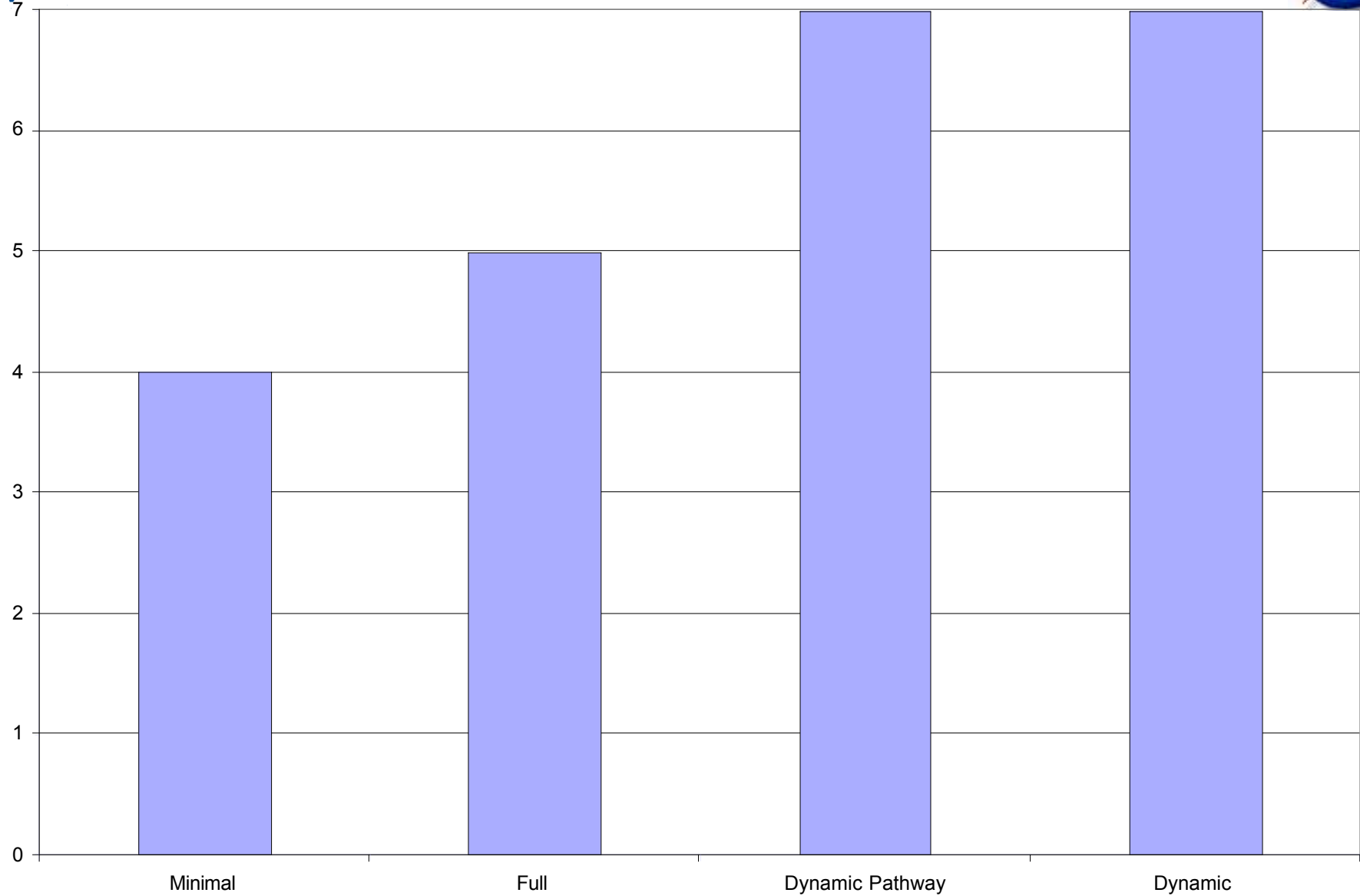
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Effectiveness of Tunnel To Re-Enter Tunnel

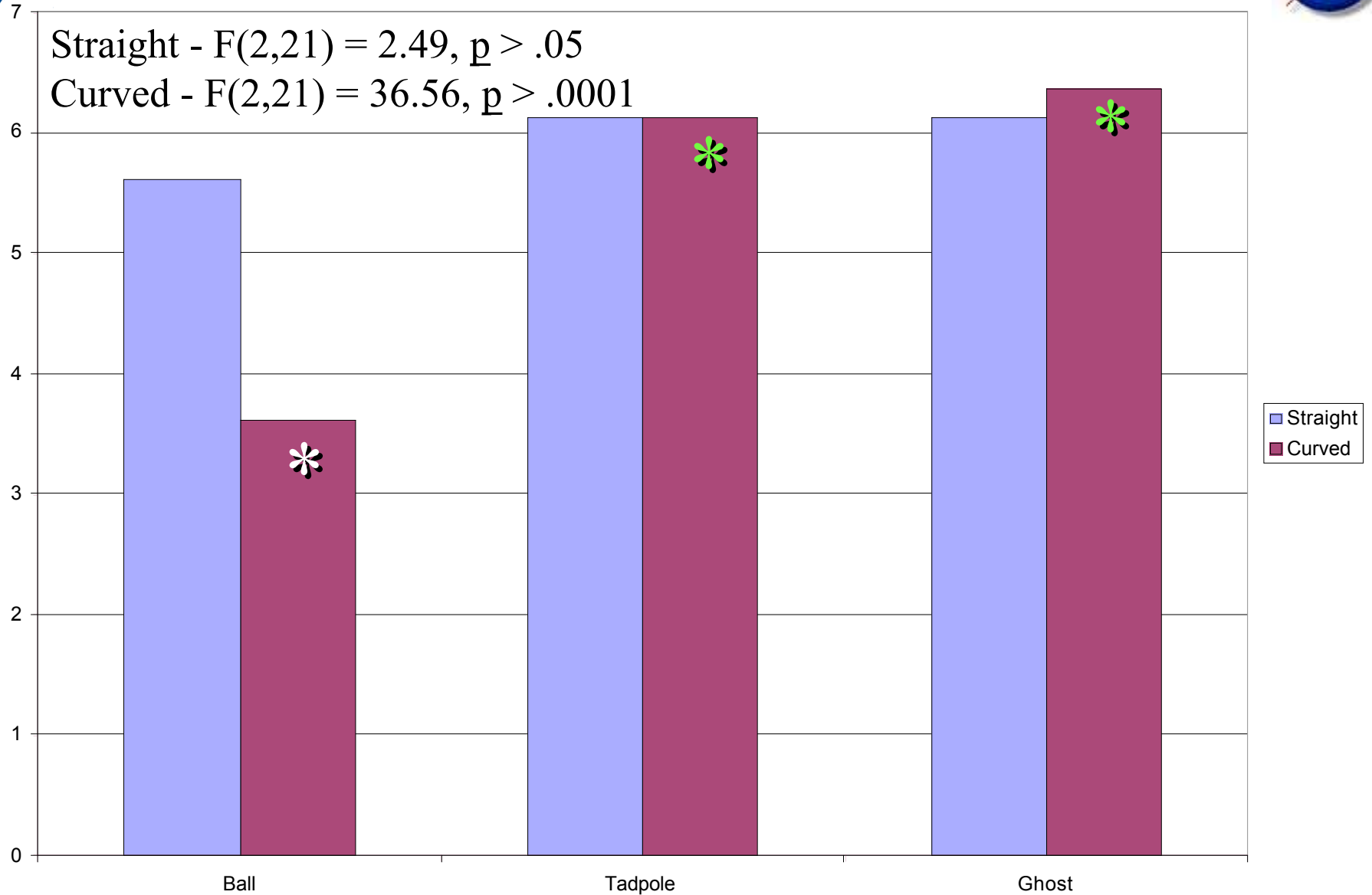
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Effectiveness of Guidance Symbology

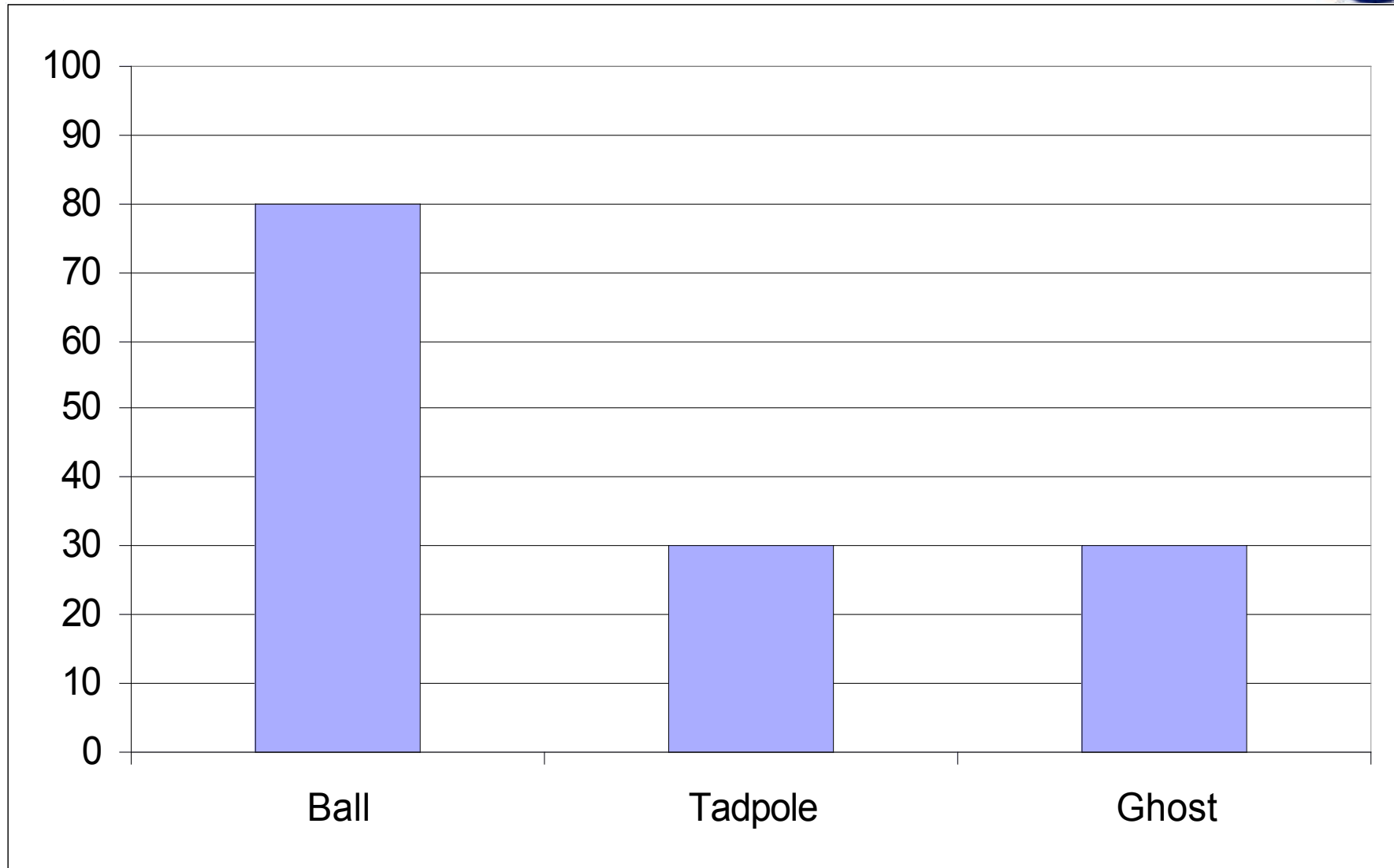
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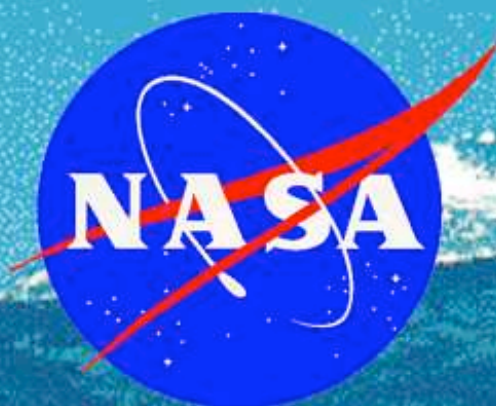
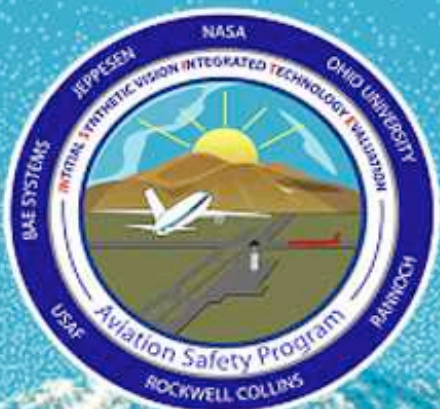




% SA Enhancement Provided by Tunnel

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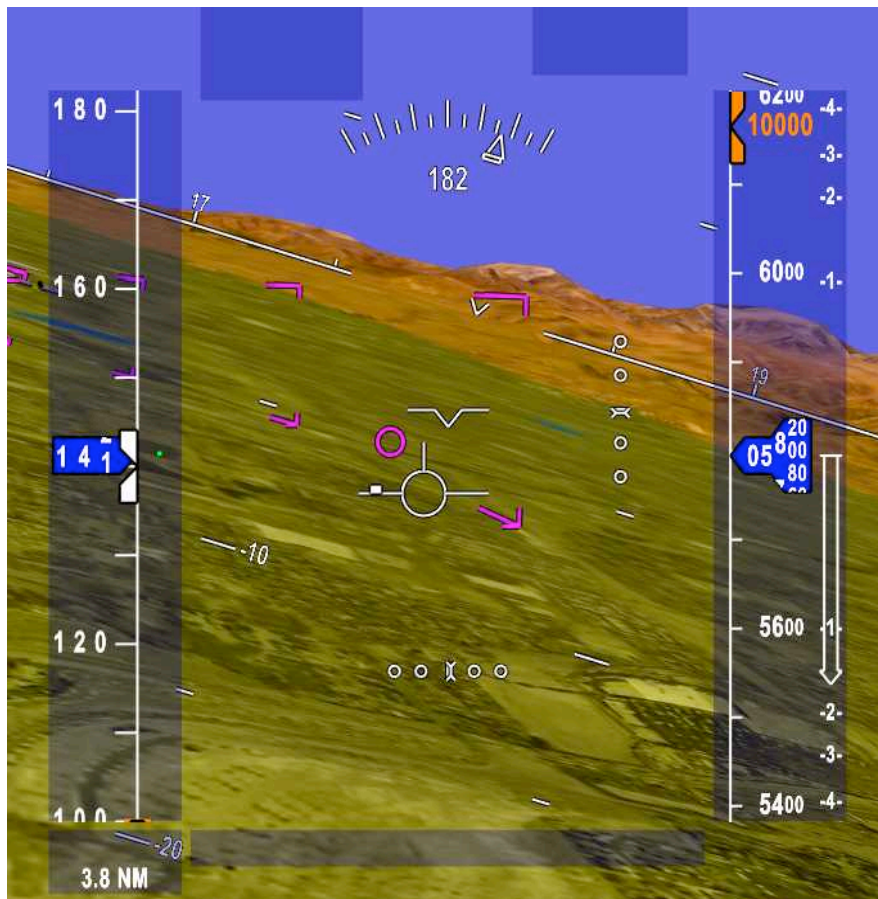
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Rare Event Results

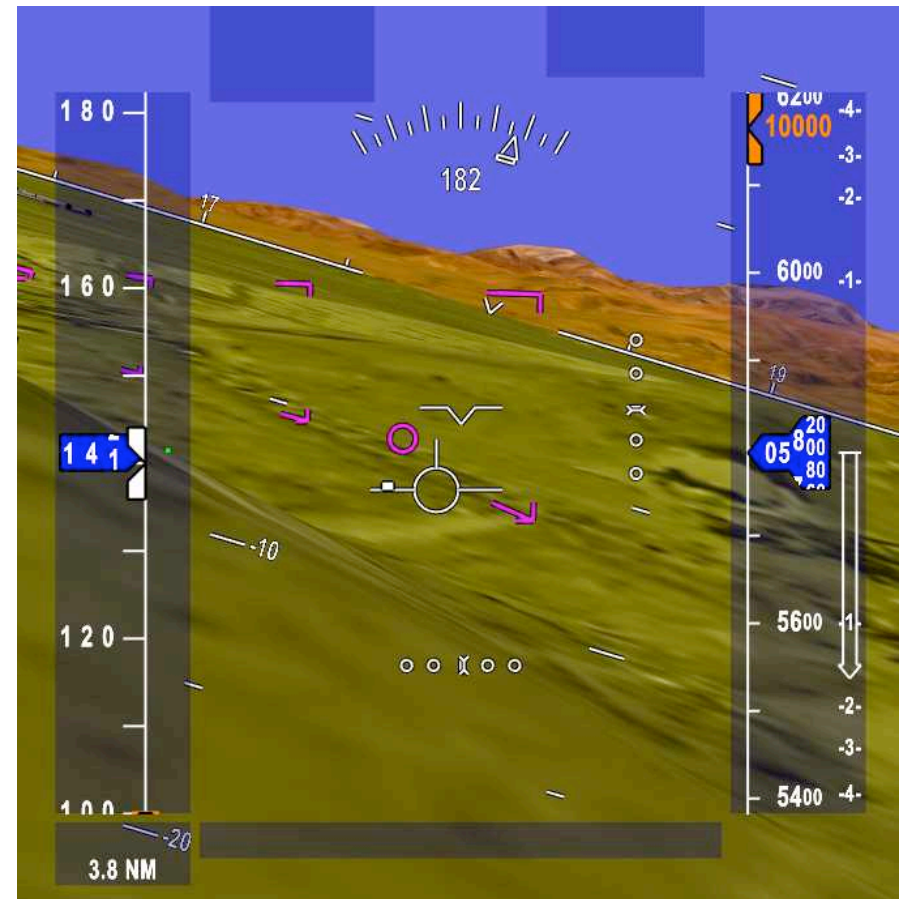


Database Error Rare Event

Aviation Safety Program: Synthetic Vision Systems



Nominal Run



Rare Event Run

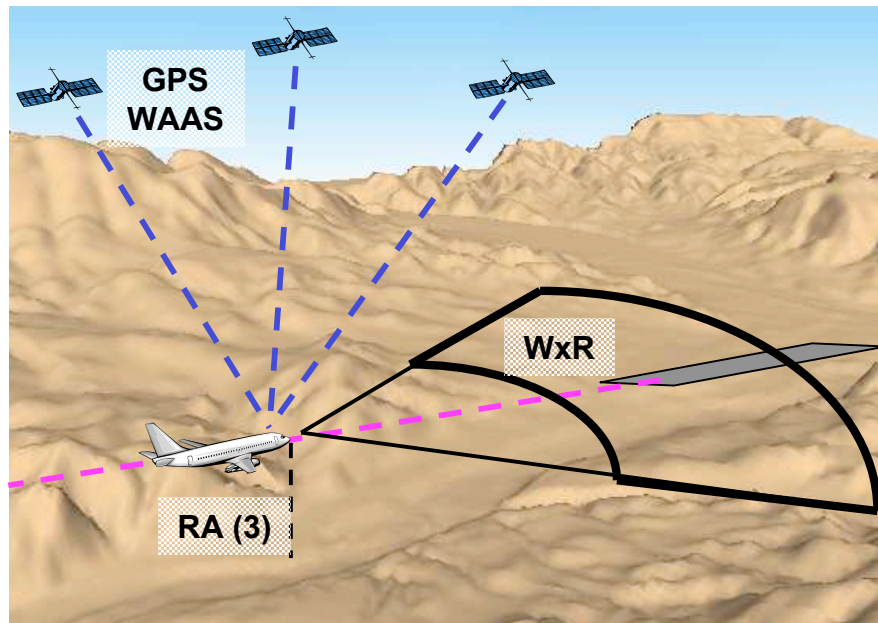


Rare Event Results

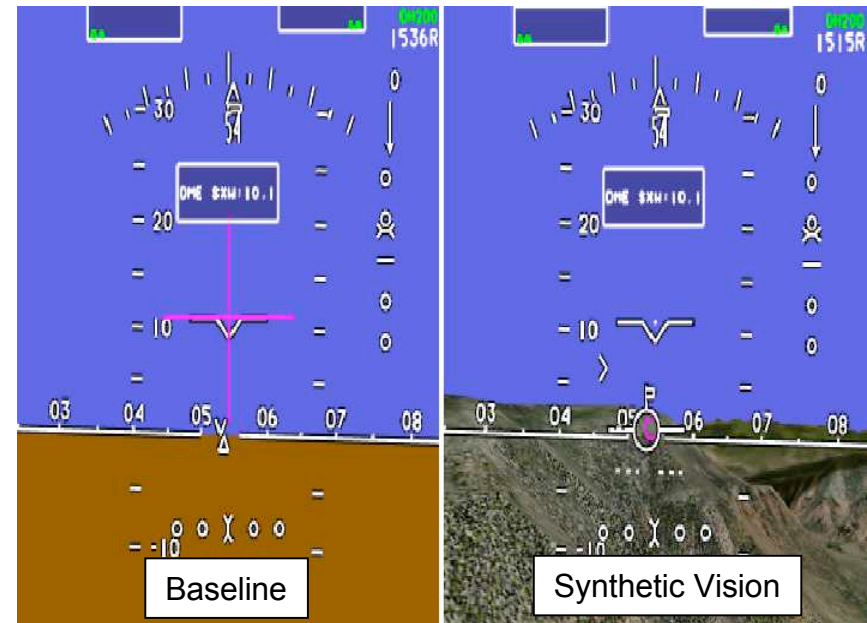
Aviation Safety Program: Synthetic Vision Systems



- 0% of pilots noticed the anomaly in time with both the Full and Minimal tunnel concepts
- 100% of pilots noticed the anomaly in time with both the dynamic pathway and dynamic crow's feet tunnel concepts



Database Integrity Monitoring



CFIT Experiment



Head-Up Display Tunnel Experiment (HINSITE)

Aviation Safety Program: Synthetic Vision Systems

